

MicroTRAK/P18 Training & Project Kit

for PIC® Microcontrollers

User's Guide

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WARRANTY:

BiPOM Electronics warrants MicroTRAK for a period of 1 year. If the product becomes defective during this period, BiPOM Electronics will at its option, replace or repair the product. This warranty is voided if the product is subjected to physical abuse or operated outside stated electrical limits. BiPOM Electronics will not be responsible for damage to any external devices connected to the microcontroller system. BiPOM Electronics disclaims all warranties express or implied warranties of merchantability and fitness for a particular purpose. In no event shall BiPOM Electronics be liable for any indirect, special, incidental or consequential damages in connection with or arising from the use of this product. BiPOM's liability is limited to the purchase price of this product.

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INTRODUCTION

The PIC® micro-controller, introduced by Microchip in the early 90's, is one of the most popular micro-controllers in use today with applications ranging from industrial, medical, home automation to automotive.

The objective of the MicroTRAK is to give students, engineers, technicians, hobbyists and other users experience with micro-controllers by developing practical applications using C and Assembly language.

The MicroTRAK Lab Book consists of several labs that vary from simple to complicated.

When used in a school environment, it is recommended that the labs accompany a micro-controller course during the semester. Depending on the duration of each lab during the week, each lab in the student manual can be covered during one or two lab weeks. Based on the remaining time during the semester, the instructor may have the students work on one or more advanced projects. Some advanced project ideas are listed in **Advanced Project Ideas** section of this manual.

This User's Guide is intended for the instructor to get familiar with and setup the MicroTRAK for the upcoming labs. The MicroTRAK Lab Book should be given to each student group in the lab to perform various exercises during the semester.

MicroTRAK can also be used as a Project Kit for rapid prototype development and proof-of-concept. Keypad, LCD, microcontroller board and peripheral boards are already mounted on the carrier board, resulting in a presentable and single-piece assembly for demonstration purposes. LCD and keypad also facilitate software debugging.

MicroTRAK consists of:

- MINI-MAX/P18 Micro-controller Board
- Training Board (TB-1), PROTO-1 Prototyping Board
- LCD with backlight (adjustable brightness) , matrix keypad
- Carrier board with extra regulator, I/O Module
- MPLAB with Assembler, Debugger and Simulator (free download from Microchip web site)
- Micro-IDE Integrated Development Environment with support for MPLAB from Microchip
- Serial cable, Power Supply
- Example Lab book and this User's Guide

The following external items are required for each Training Kit station:

- Personal Computer (PC) with
- Minimum 128MB memory and 1GB of available hard disk space.
- One available RS232 Serial Port.
- Windows 98/ME/NT/2000/XP/Vista/Windows 7 (32-bit or 64-bit).
- (Optional) Digital Voltmeter

INSTALLATION

Installing the Hardware

Place MicroTRAK on a clean, **non-conductive** bench top (preferably on an anti-static mat)

Connect the provided power supply to the power plug on the MicroTRAK . Do not connect the power supply to the outlet yet.

CAUTION: Do not use a power supply other than the one that is supplied with the MicroTRAK . Use of another power supply voids the warranty and may permanently **DAMAGE** the board or the computer to which the board is connected !

Make sure the PC is powered off.

Connect one end of the RS232 serial cable to serial connector of MINI-MAX/P18 board as shown on Figure 1.

Connect the other end of the serial cable to your PC's COM port.

Connect the 6VDC power supply to a suitable wall outlet. Power LED on MicroTRAK Carrier Board will turn ON.

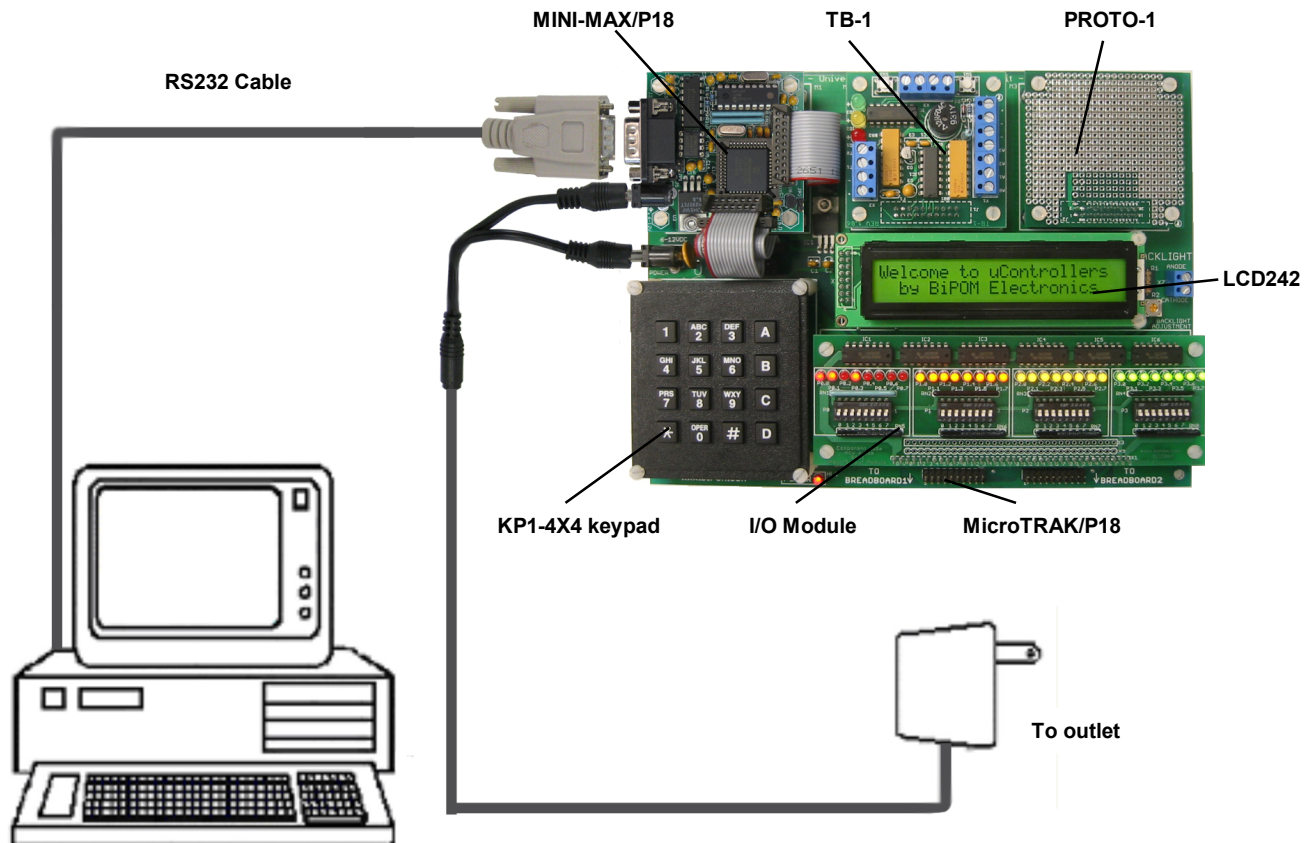


Figure 1

Installing the Software

Software for the system consists of two packages:

1. Micro-IDE from BiPOM Electronics: This is a free download.
2. MPLAB from Microchip: This is also a free download.

Micro-IDE

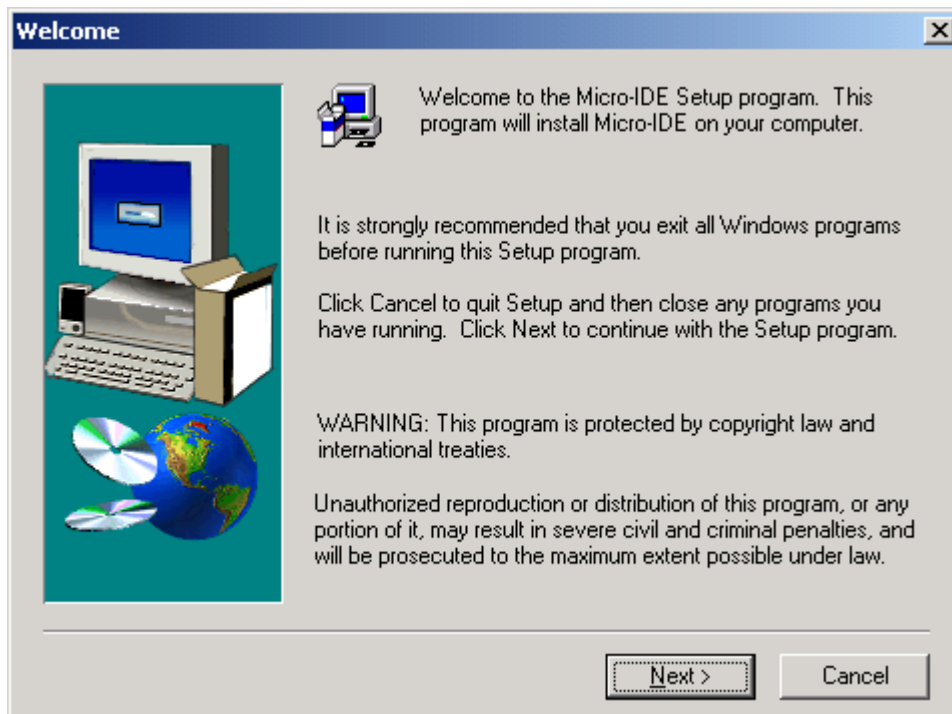
Micro-IDE is an Integrated Development Environment for micro-controller systems application development. Micro-IDE integrates essential components of software development including:

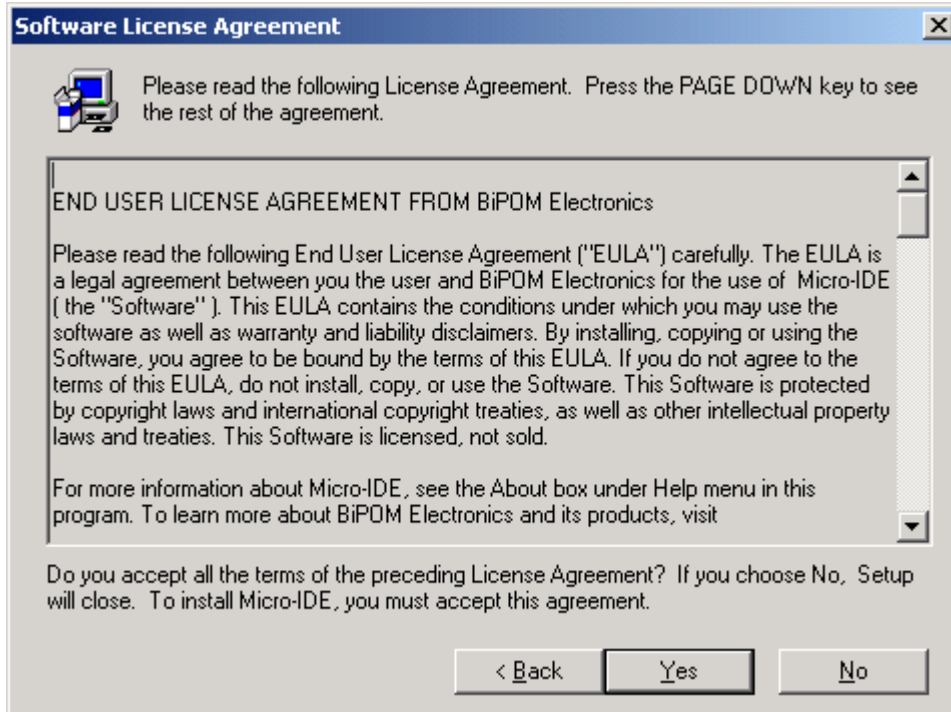
- Multi-File Editor
- Project Manager
- C Compiler, Assembler, Linker
- Optional Micro-controller Simulator
- Terminal program, Calculator, ASCII Chart
- Serial Port Loader

Since Microchip's MPLAB has similar features, we will use MPLAB as our main development environment and use Micro-IDE only as a serial downloader and serial terminal.

Micro-IDE is a part of BiPOM's MC Development System:

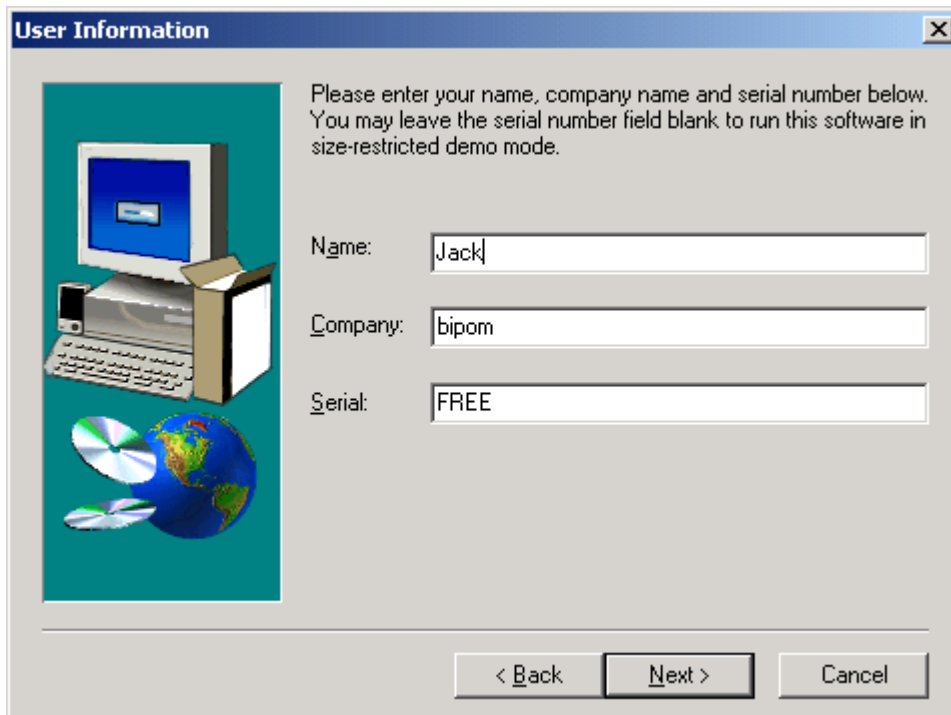
Download and run **pic_devsys.exe** from http://www.bipom.com/web_softwares/318931.html



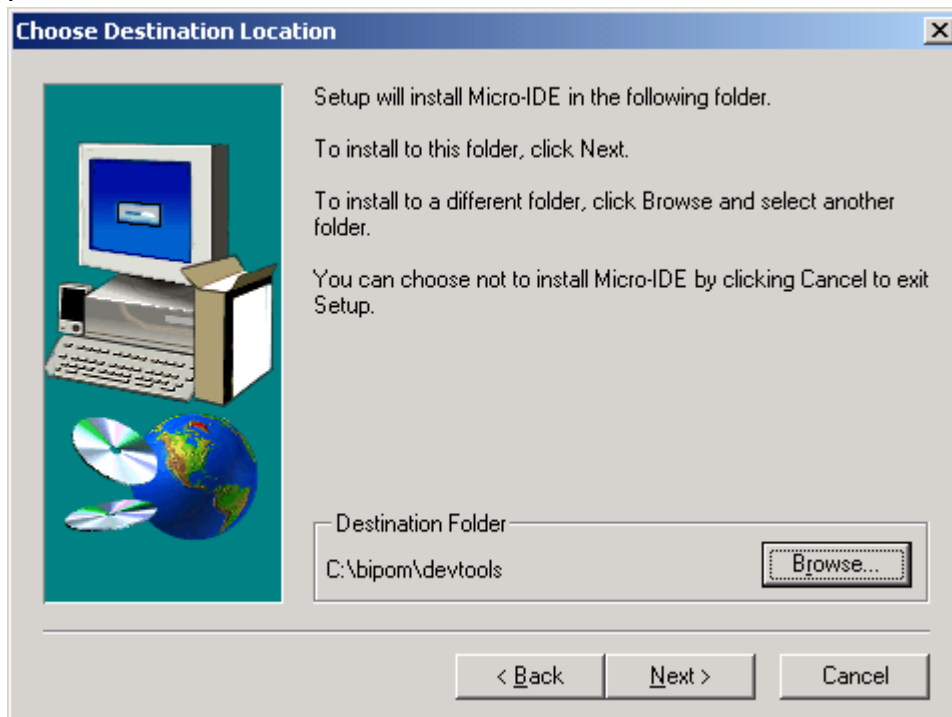


Please read the agreement and click Yes to continue.

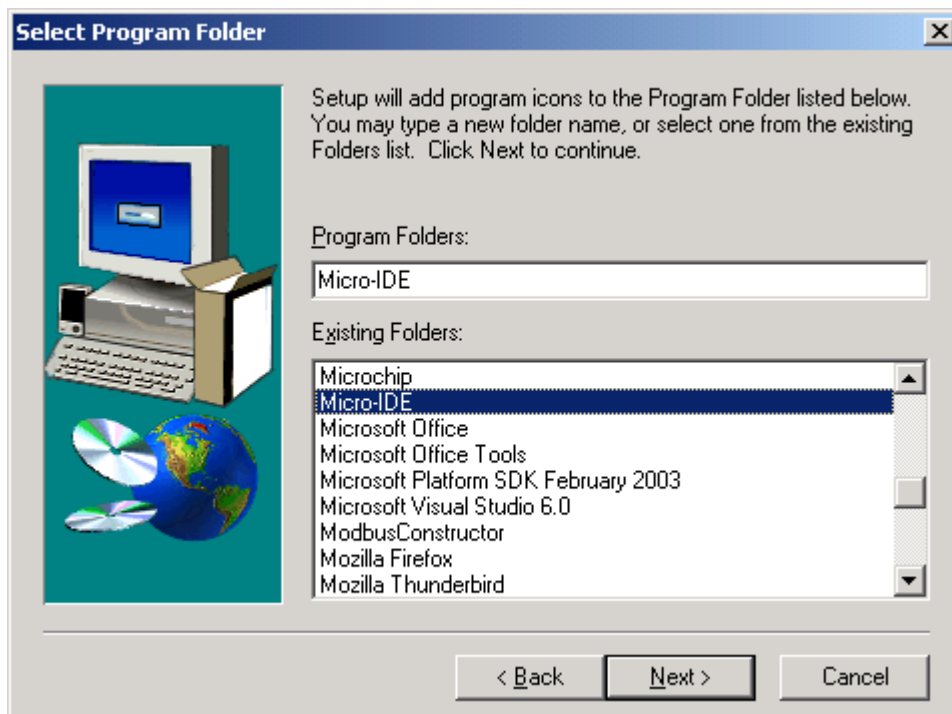
Enter your name, company and 'FREE' as a serial number. Then click the Next button.



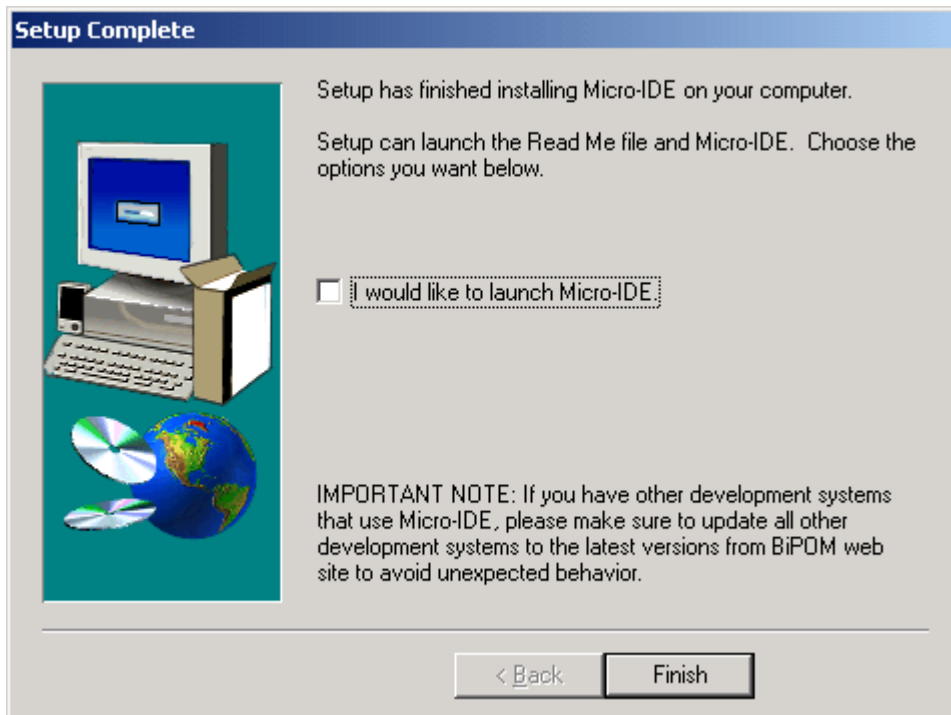
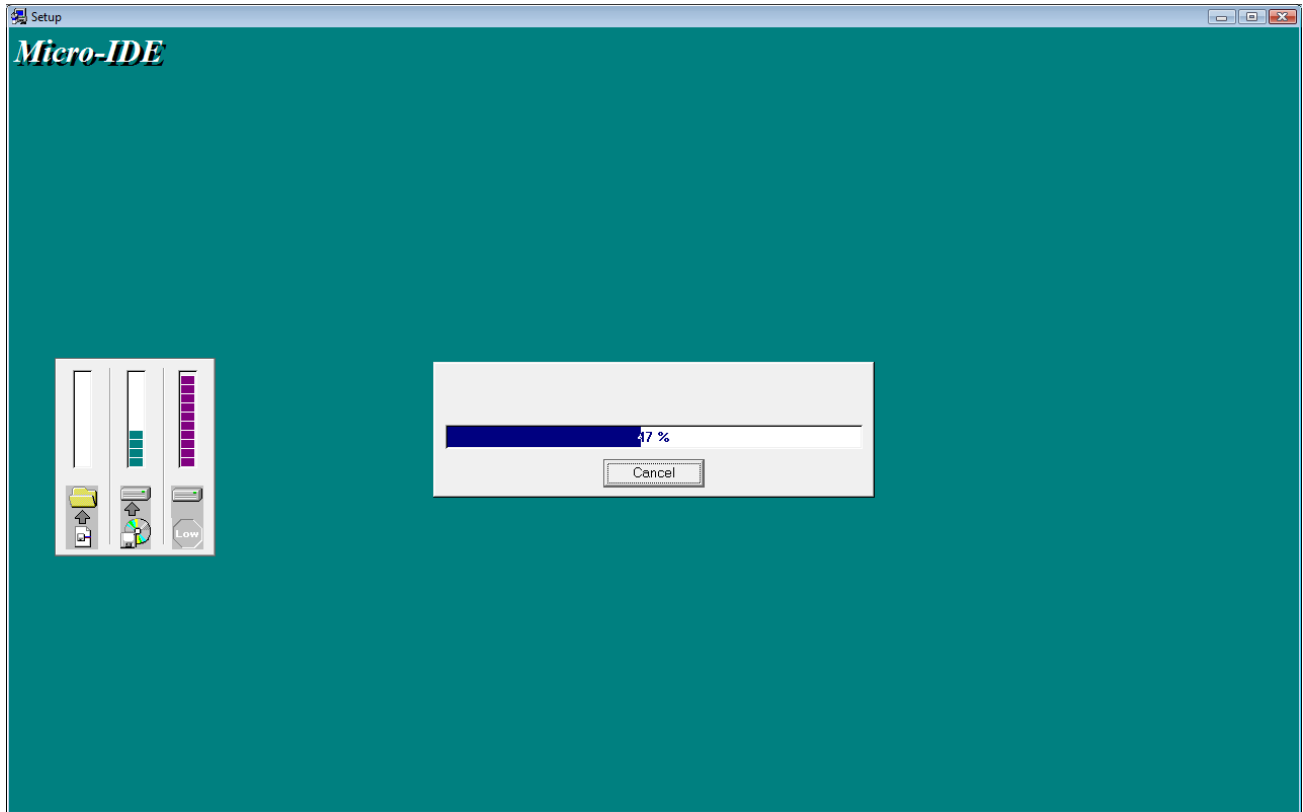
Select the disk location where the software has to be installed. The default location (c:\bipom\devtools) is recommended. Click the Next button to start the installation.



Click Next. Select the Program Folder where the icons for Micro-IDE will be installed. Default selection is **Micro-IDE** folder:



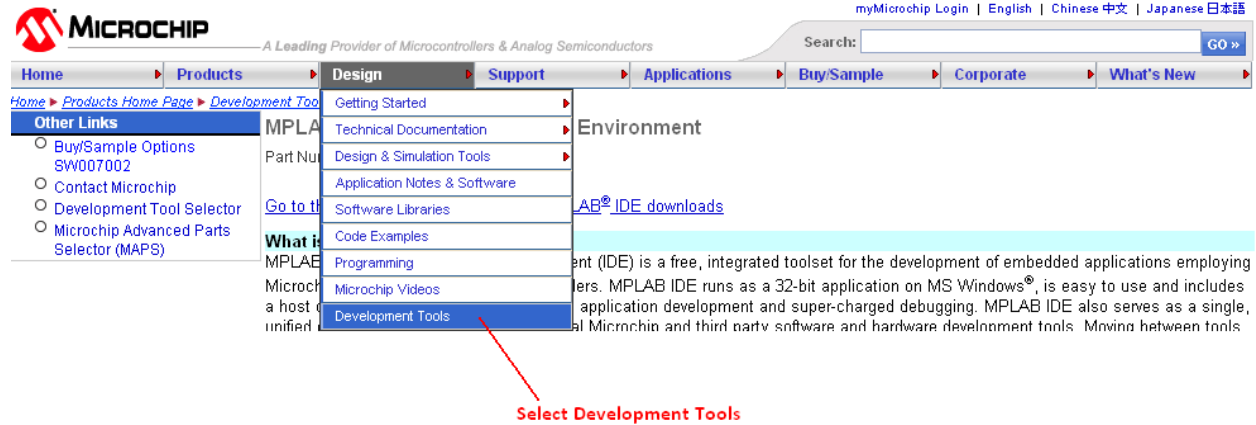
Click Next. Micro-IDE will be installed.



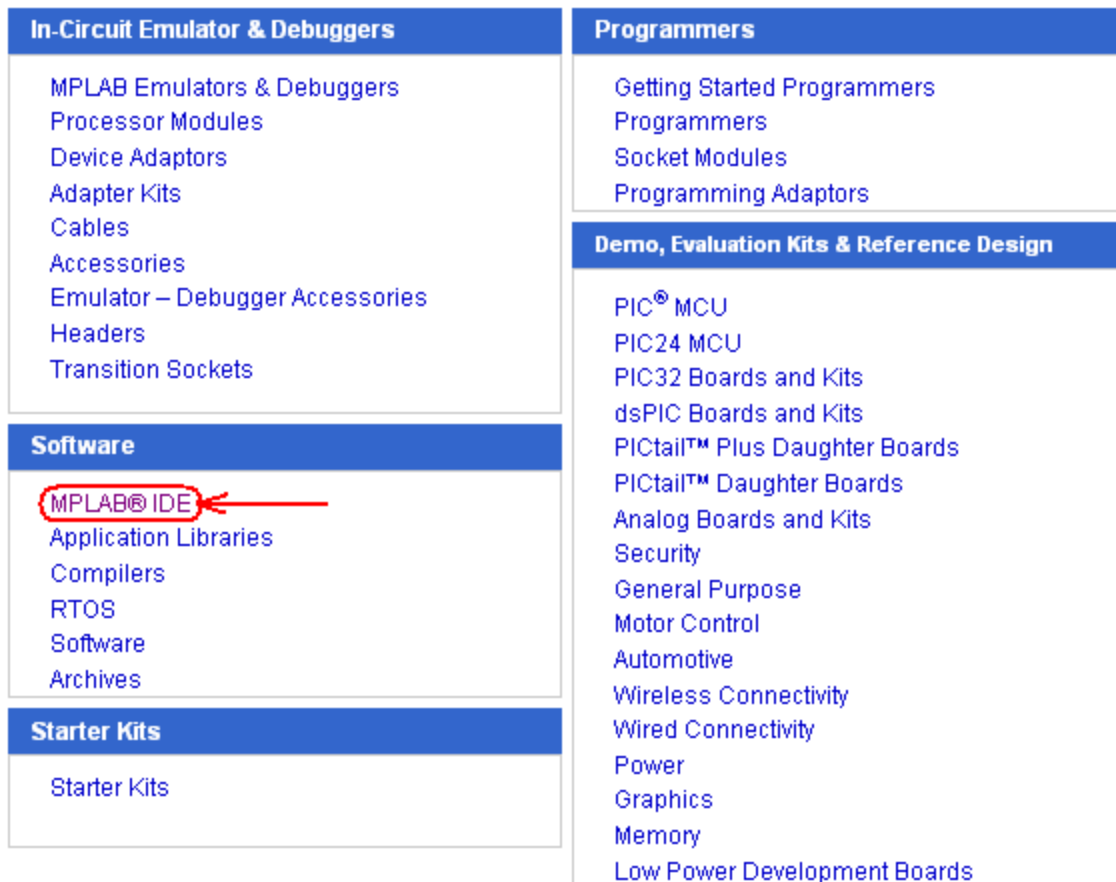
Uncheck the "I would like to launch Micro-IDE" option and click the Finish button.

MPLAB

Download and install the latest **MPLAB® IDE** from **Microchip®** website. The location of MPLAB on Microchip web site may change from time to time. To find the latest MPLAB, please visit www.microchip.com first. Select Development Tools from Design tab:



Download MPLAB IDE:



Latest Production Release: MPLAB IDE v8.56

New in MPLAB IDE v8.56:

The most recent full release of MPLAB IDE introduces these new features:

These new features are added to MPLAB IDE v8.56 (new device support is listed in the Release Notes):

New part support – See Release Notes for details.

Bug fixes –

Please direct any comments or questions about MPLAB IDE to the [MPLAB IDE Online Discussion Group](#) in the Development Tools Forum or to <http://support.microchip.com>.

Archived versions of older MPLAB IDE software are available [here](#).

If you have problems with the installation check <http://consumer.installshield.com>.

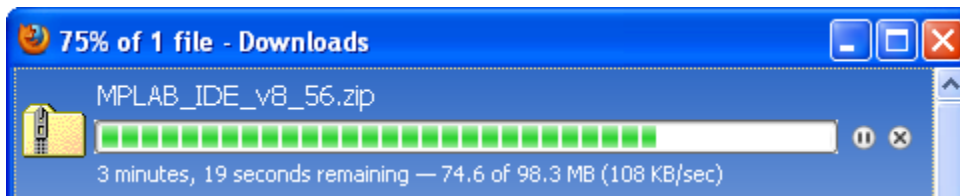
If you have any difficulties downloading any of these files, please e-mail webcorrections@microchip.com

MPLAB Software	
Downloads	Associated Files and Release Notes
MPLAB IDE v8.56 Full Release Zipped Installation	Release Notes for MPLAB IDE v8.56
MATLAB Device Blocks for dsPIC DSCs	

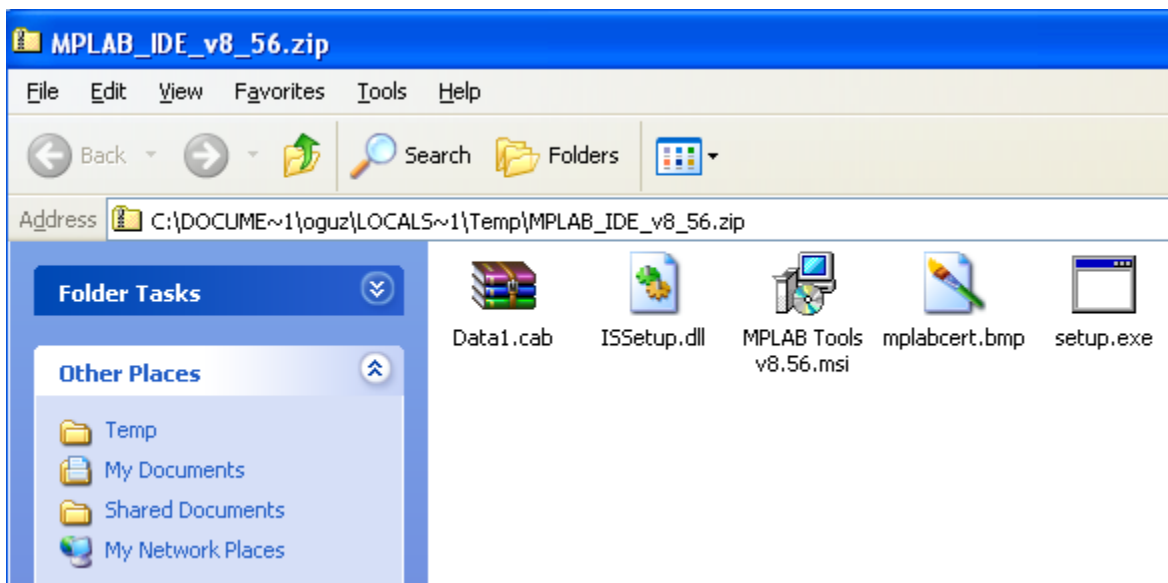
Downloads

Title	Date Published	Size	D/L
MPASM/MPLINK User's Guide	4/8/2009 3:52:41 PM	2896 KB	
MPLAB Assembler, Linker and Utilities for PIC24 MCUs and dsPIC DSCs User's Guide	1/26/2010 10:16:32 AM	1981 KB	
MPLAB IDE User's Guide	1/20/2009 12:09:31 PM	4232 KB	
The MPLAB IDE Debug Tool API	5/13/2010 5:16:00 PM	171 KB	

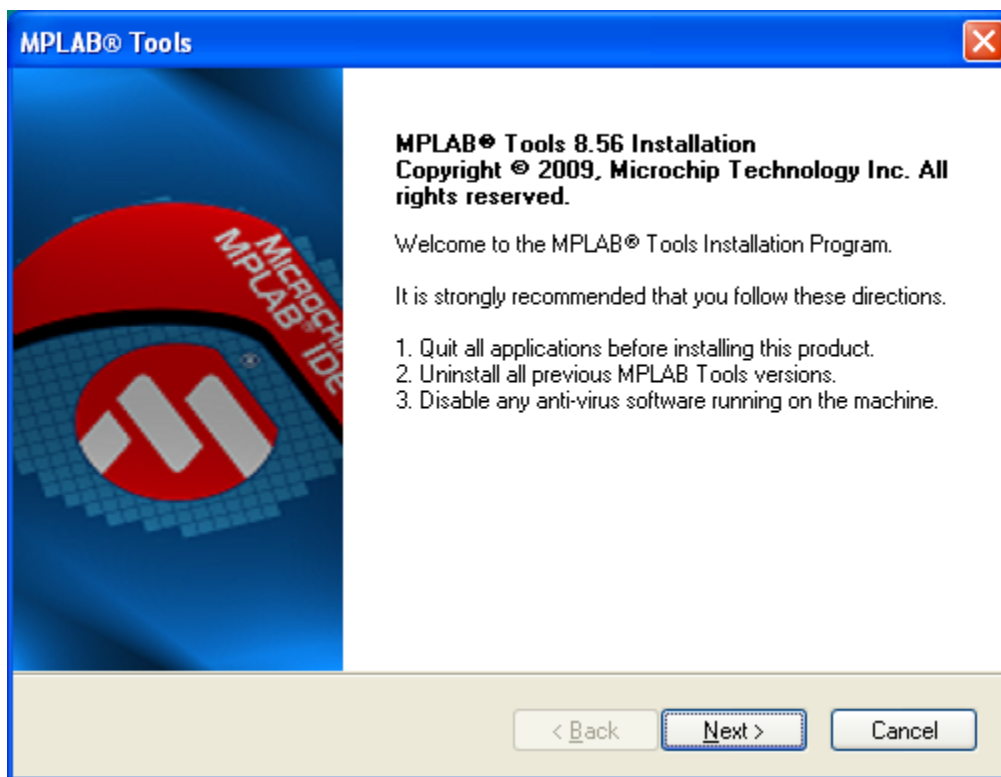
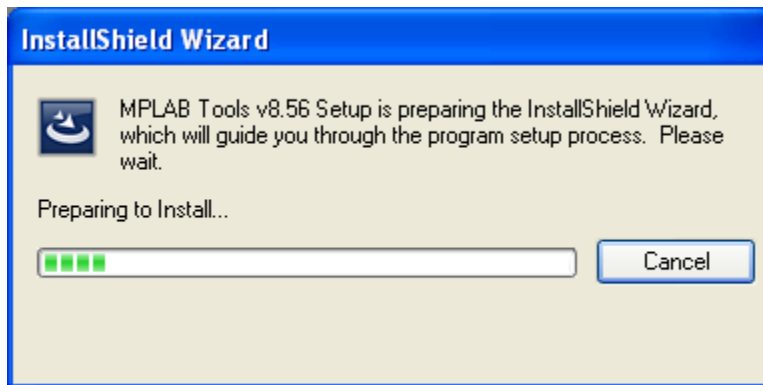
When you click on the link, zip file will start downloading:



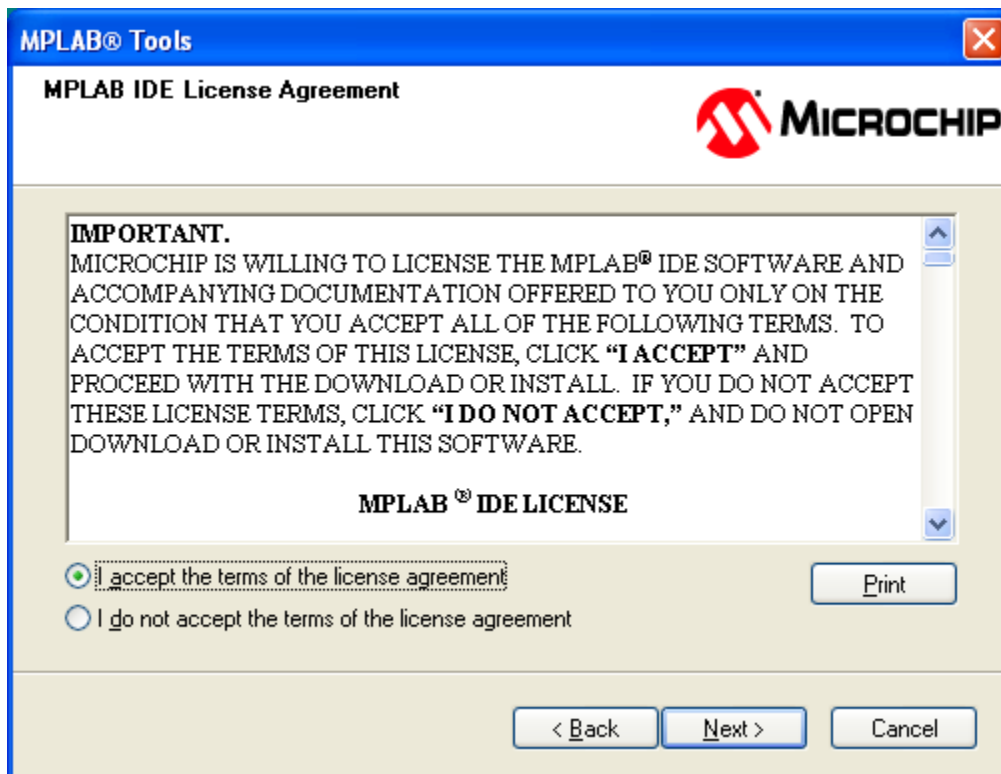
Extract the contents of the zip file to a temporary directory (for example, **c:\temp**) and run **setup.exe** from within the zip file:



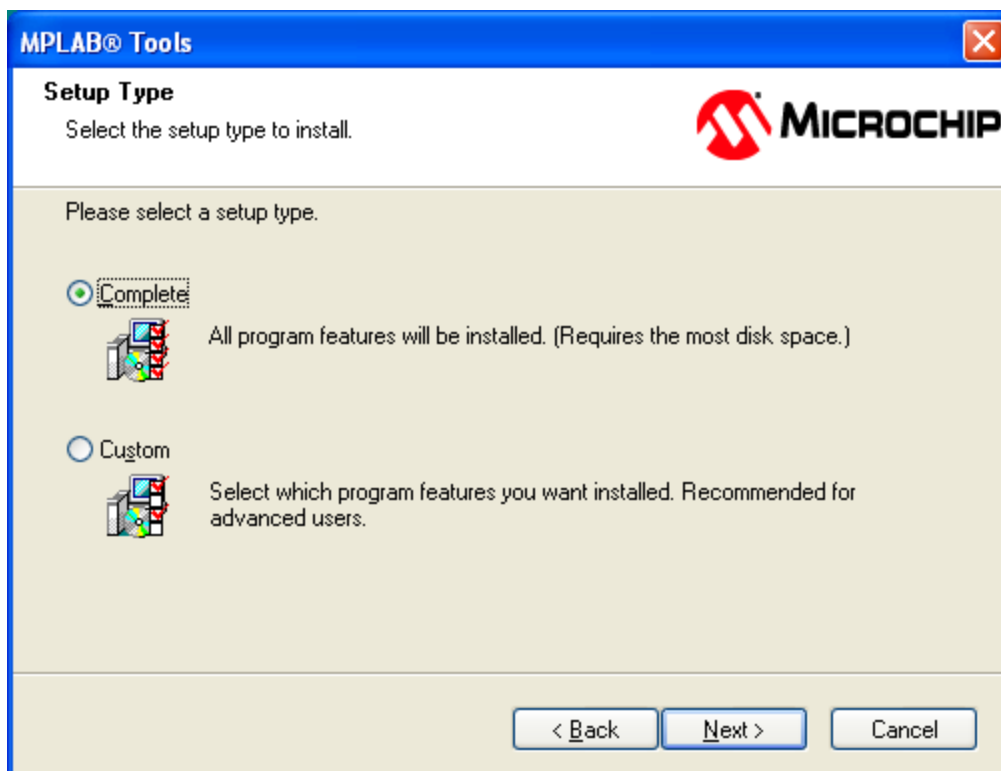
MPLAB Installation will start:



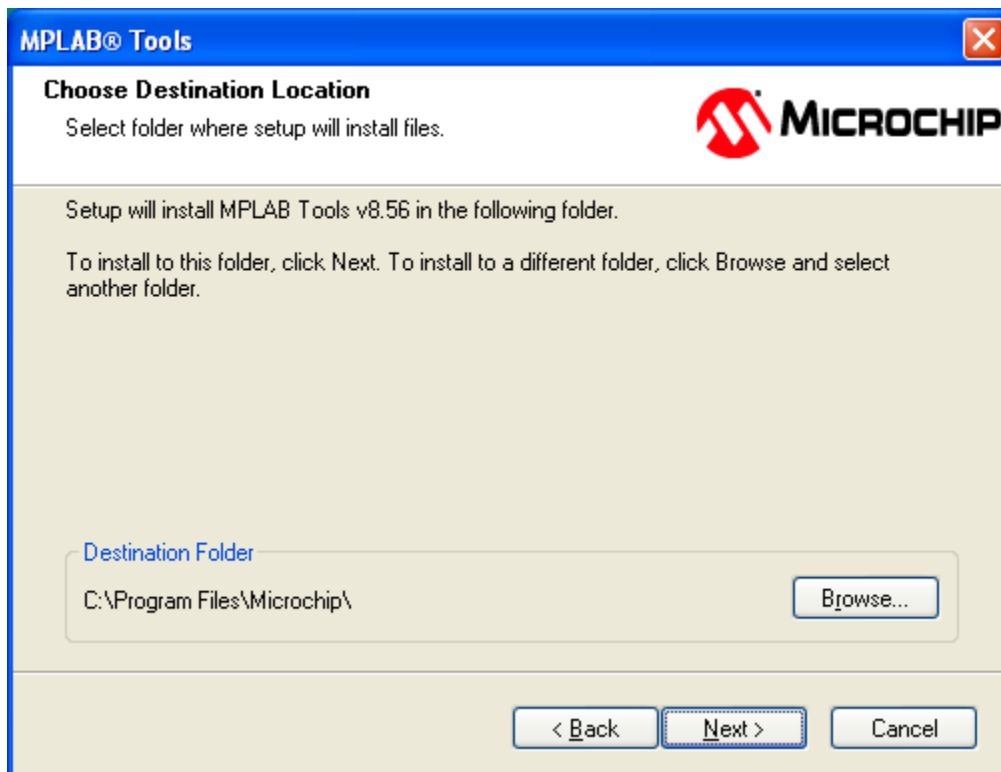
Click Next. Accept the license agreement:



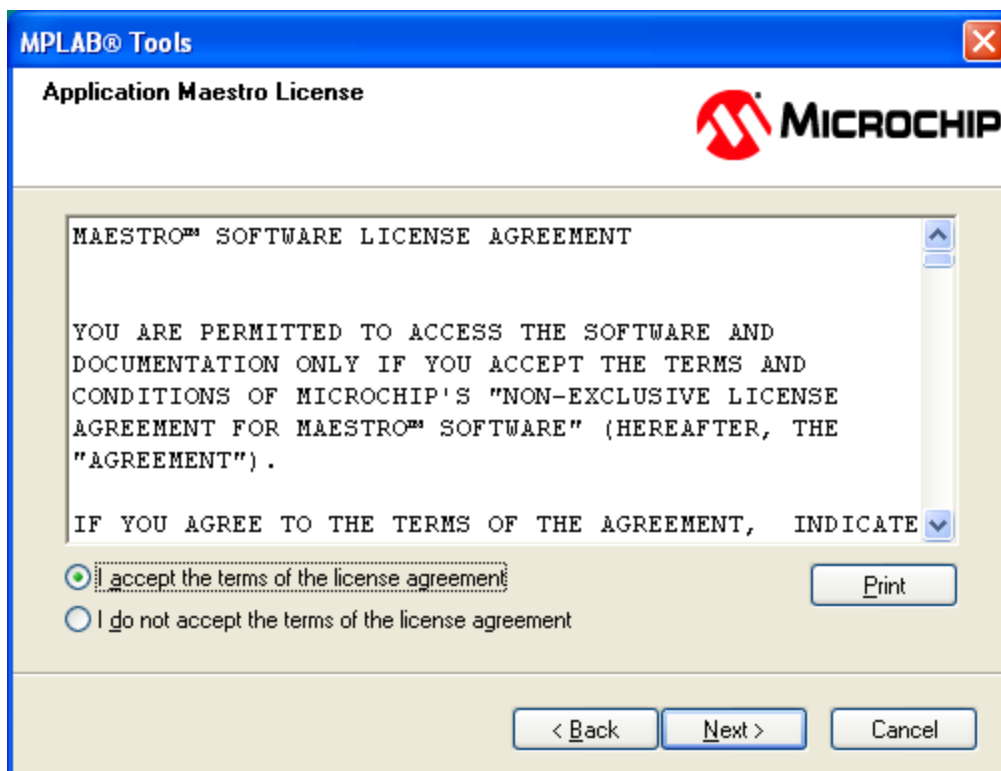
Click Next.



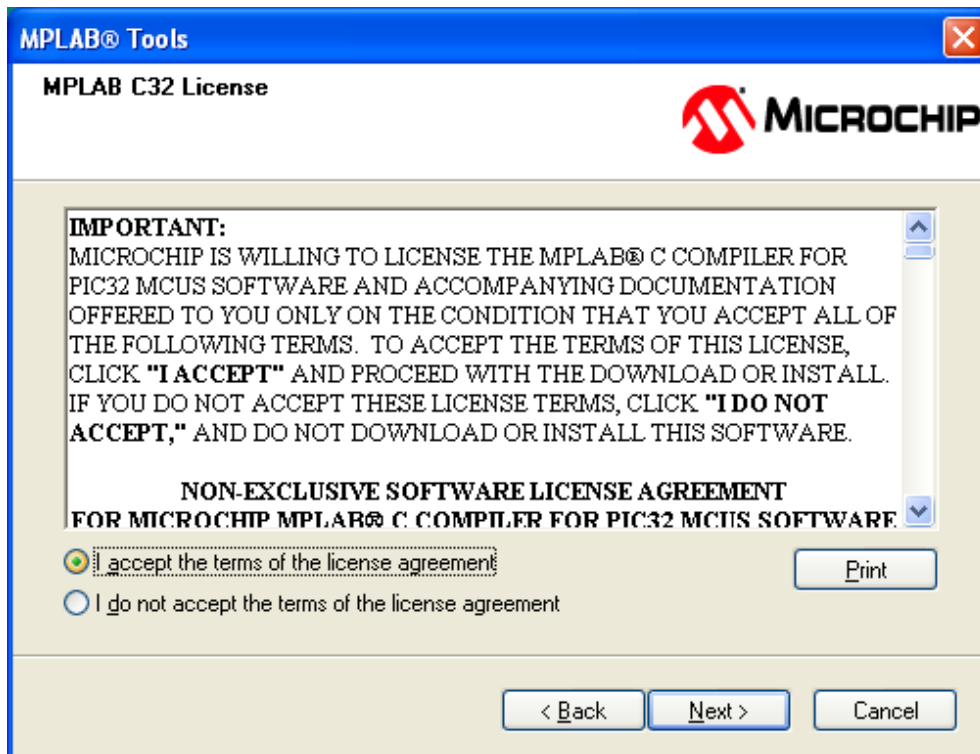
Select Complete. Click Next.



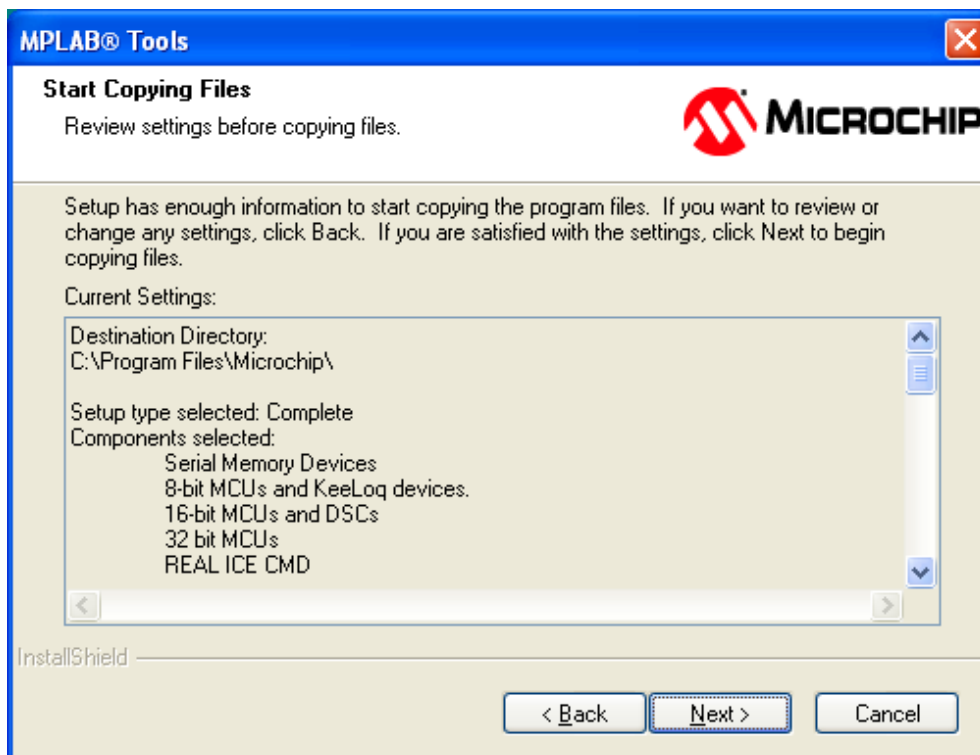
Click Next to install to default location.



Accept the agreement and click Next.

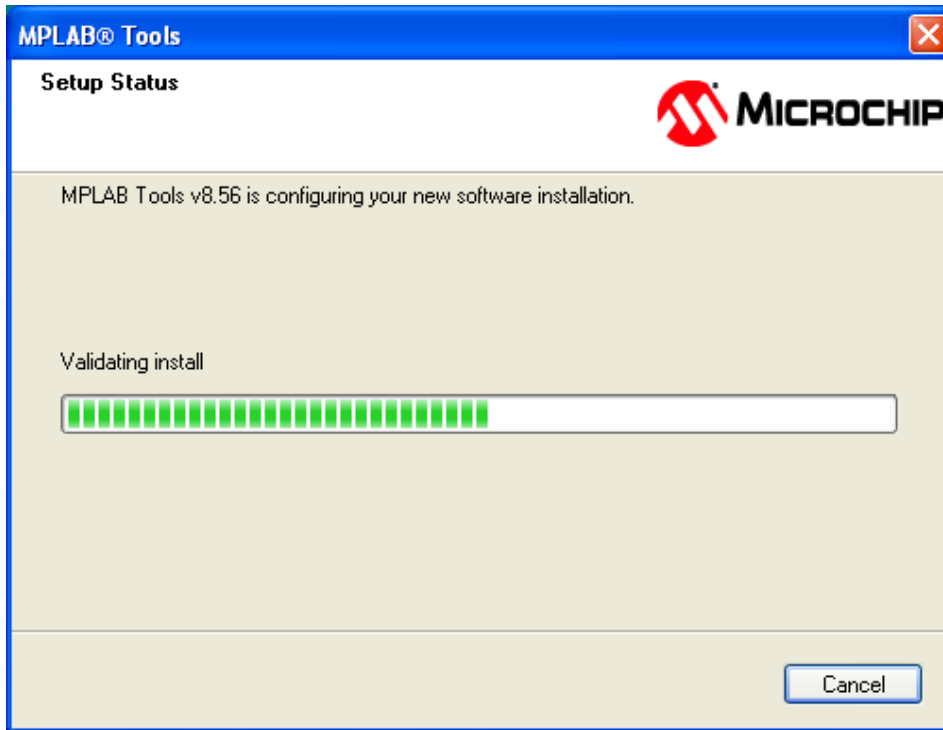


Accept the agreement and click Next.



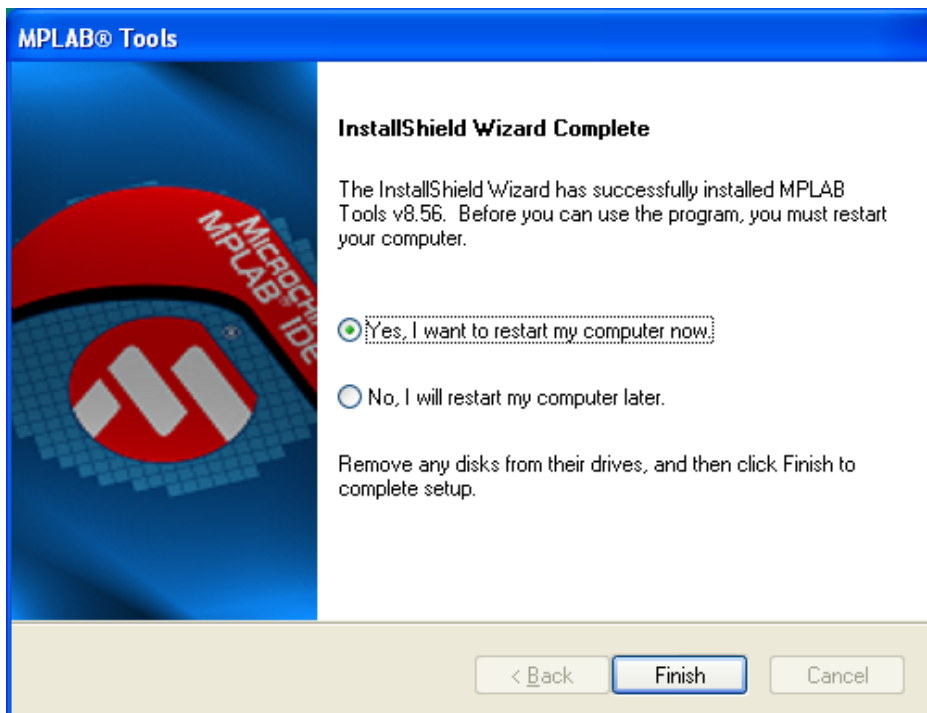
Click Next.

Installation will start:

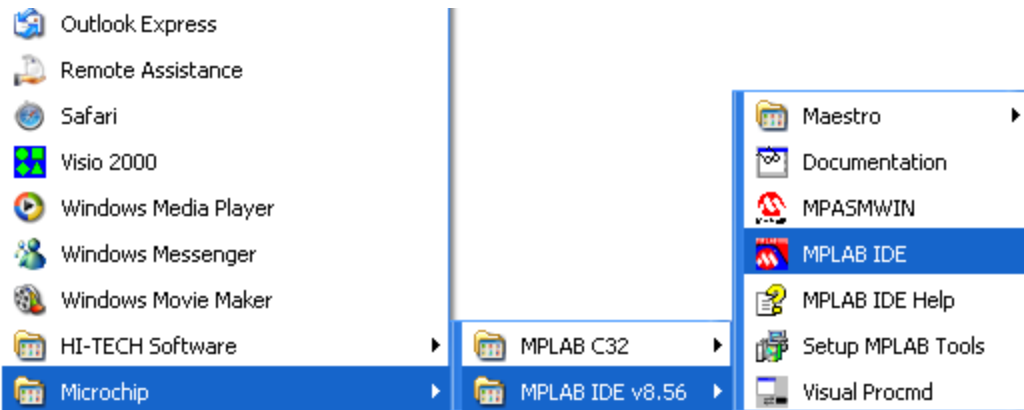


The installation program may ask you to install HI-TECH C after the MPLAB installation is complete. It is OK to click Yes and install HI-TECH C although it is not needed for the purpose of this User Guide.

At the end of installation, you may be asked to restart your computer. Make sure that all your open programs are closed and your data is saved and click Finish restart your computer:



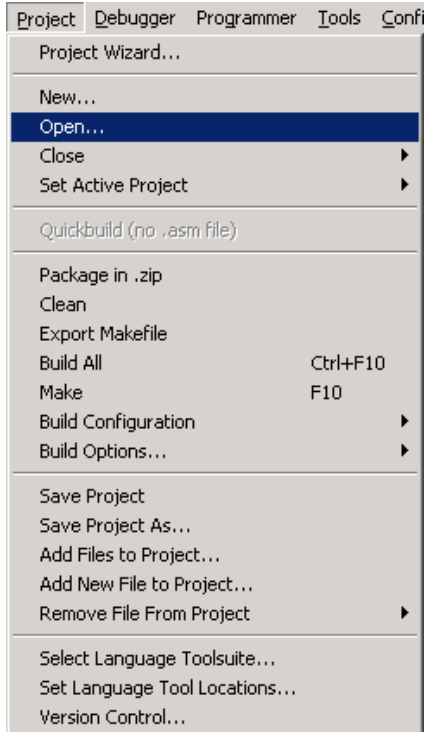
After your computer restarts, you can start MPLAB from Start->Programs:



Opening Projects

MC Development System is distributed with several example programs that illustrate how to program the PIC® micro-controller.

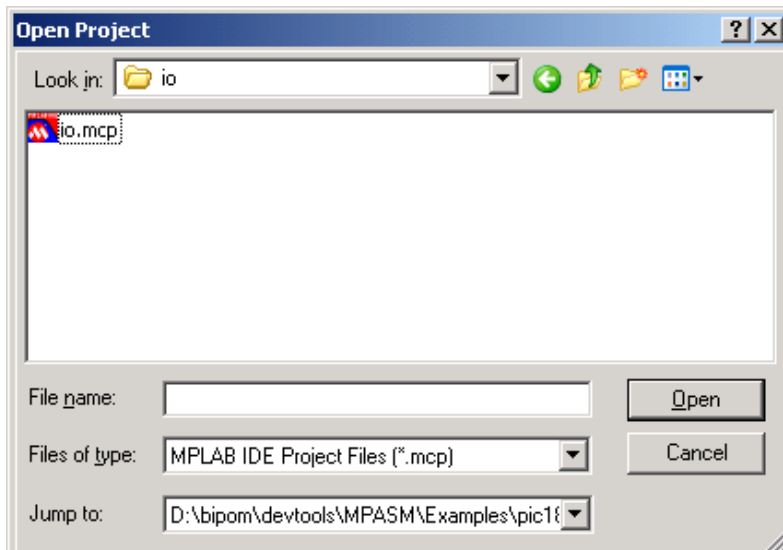
To open the example projects, start MPLAB and select Project menu. Select Open.



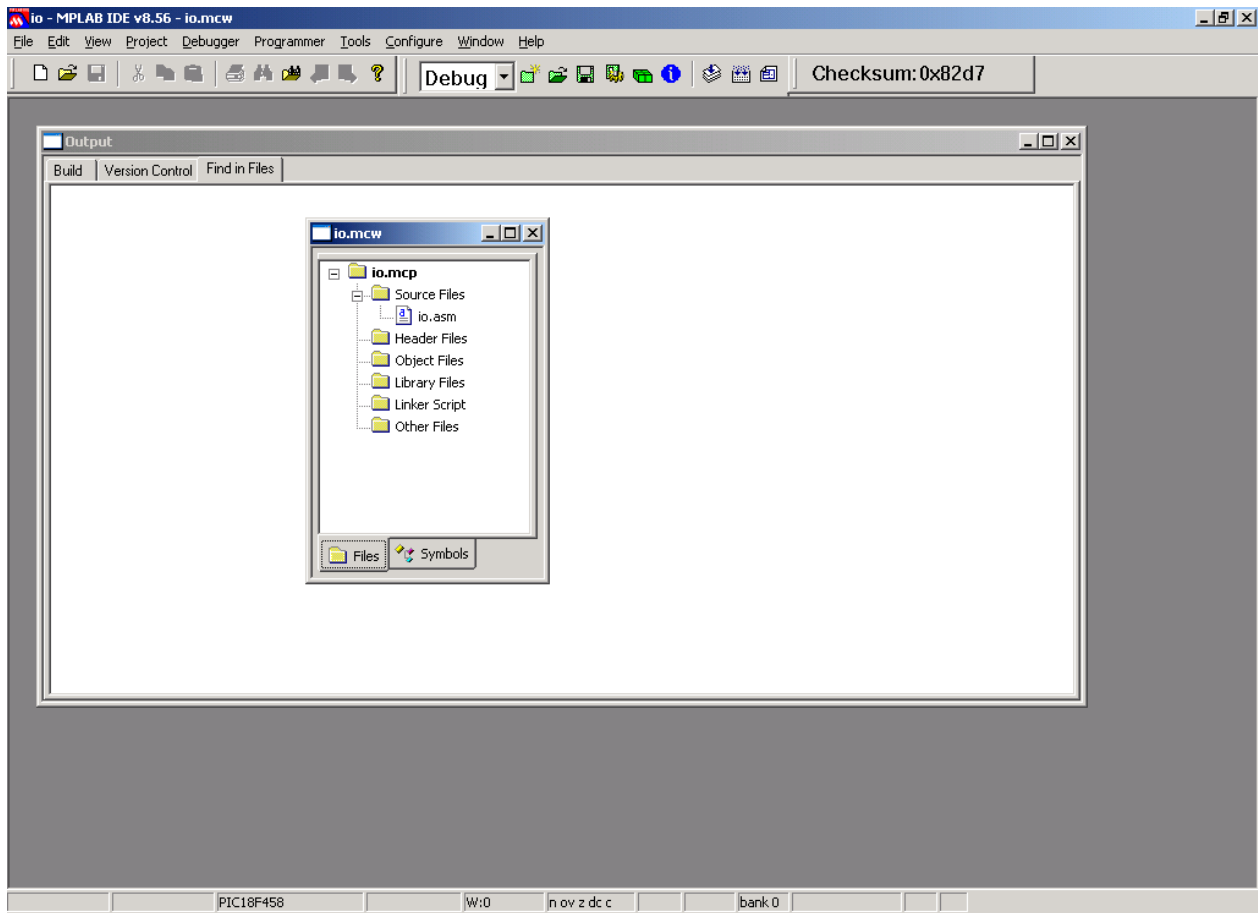
PIC18 example projects are located under the path:

\\bipom\devtools\MPASM\Examples\pic18

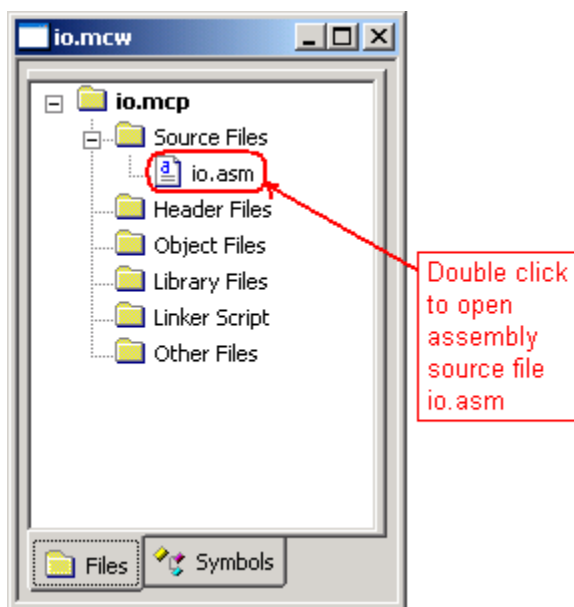
Select the project **io.mcp**:



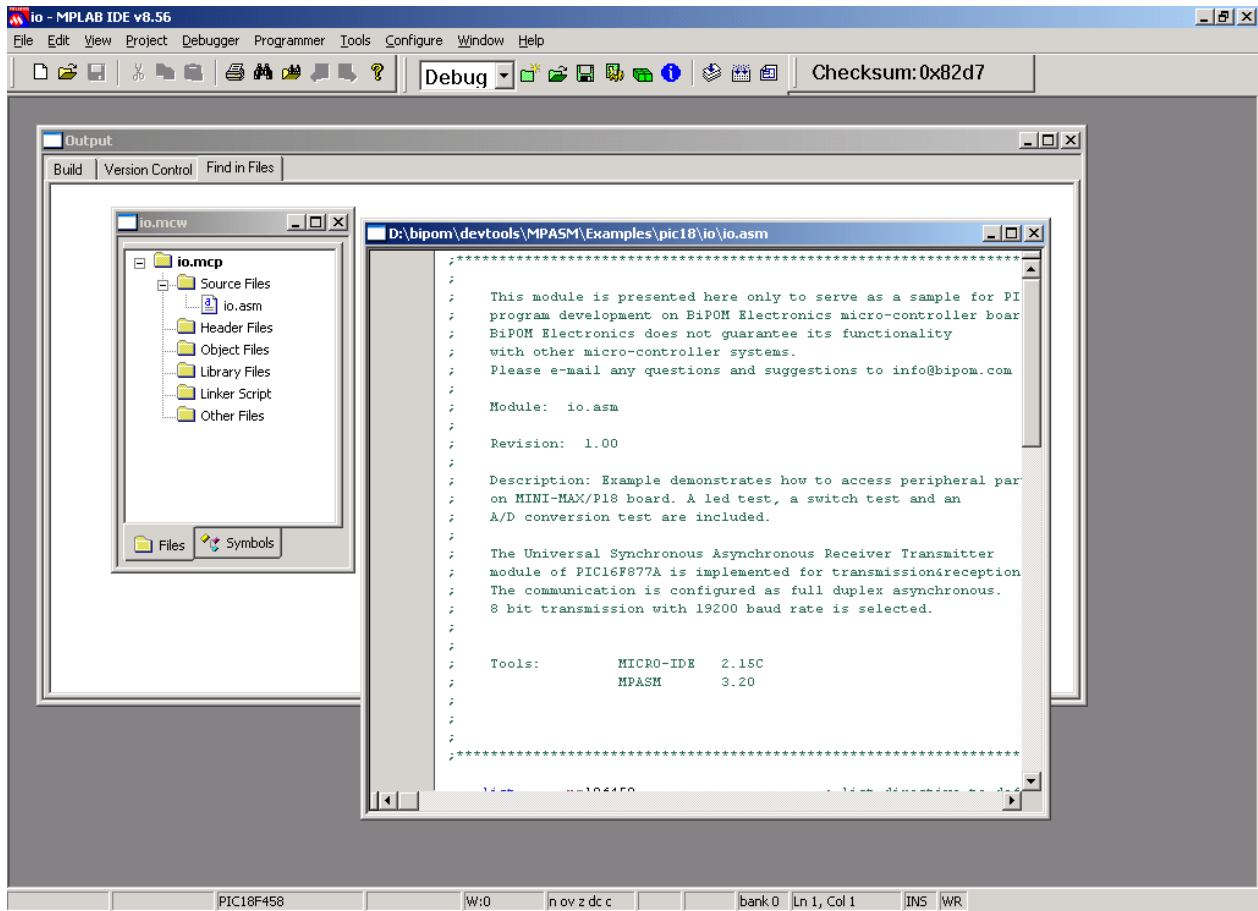
MPLAB will open the project and display the Project View:



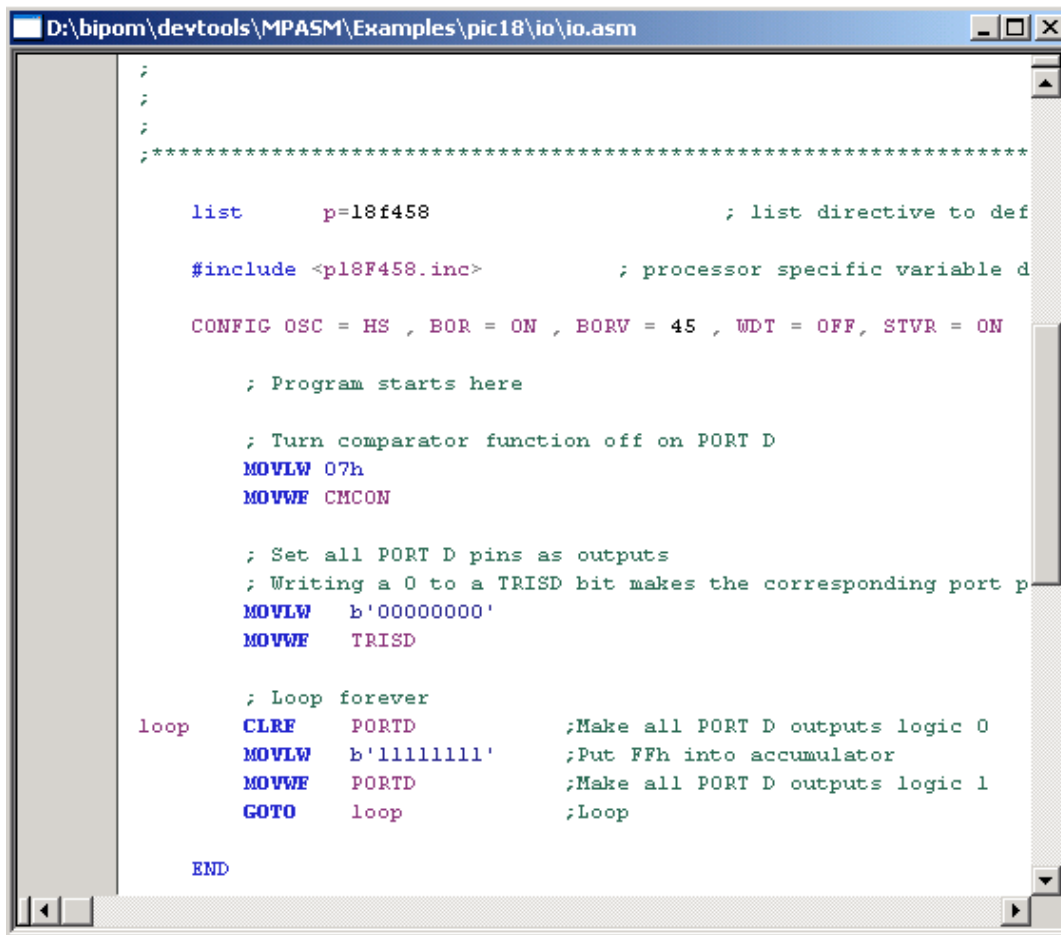
Double click on *io.asm* to open the source file:



The *io.asm* assembly language source file will appear:



You can scroll down to see the assembly instructions of io.asm:



```

;
;
;
;*****
list      p=18f458                ; list directive to def
#include  <p18F458.inc>           ; processor specific variable d
CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF, STVR = ON

; Program starts here

; Turn comparator function off on PORT D
MOVLW 07h
MOVWF CMCON

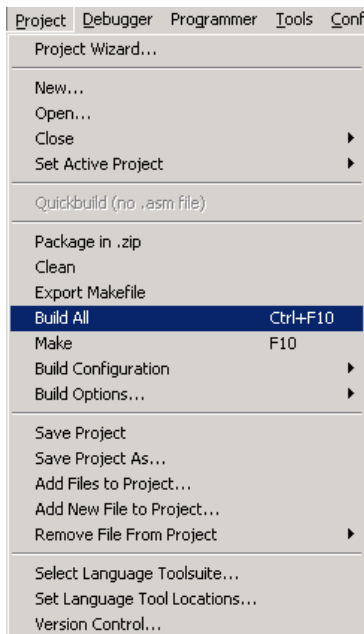
; Set all PORT D pins as outputs
; Writing a 0 to a TRISD bit makes the corresponding port p
MOVLW  b'00000000'
MOVWF  TRISD

; Loop forever
loop     CLRWF  PORTD             ;Make all PORT D outputs logic 0
        MOVLW  b'11111111'      ;Put FFh into accumulator
        MOVWF  PORTD           ;Make all PORT D outputs logic 1
        GOTO   loop            ;Loop

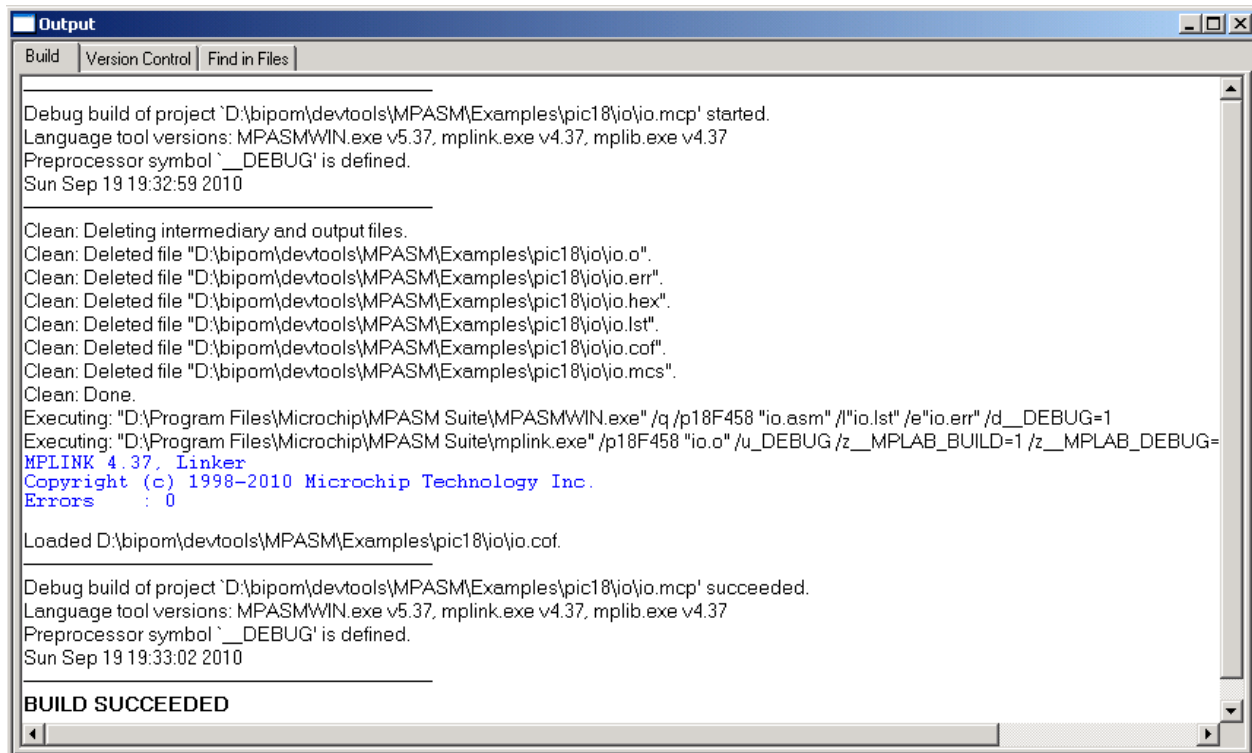
END

```

Select Project->Build All to build the project:



The project will build, *io.asm* file will be compiled and an *io.hex* output file will be generated. The results of the Build are displayed in the Build Window:



```
Output
Build | Version Control | Find in Files
-----
Debug build of project 'D:\bipom\devtools\MPASM\Examples\pic18\io\io.mcp' started.
Language tool versions: MPASMWIN.exe v5.37, mplink.exe v4.37, mplib.exe v4.37
Preprocessor symbol '__DEBUG' is defined.
Sun Sep 19 19:32:59 2010

Clean: Deleting intermediary and output files.
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.o".
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.err".
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.hex".
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.lst".
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.cof".
Clean: Deleted file "D:\bipom\devtools\MPASM\Examples\pic18\io\io.mcs".
Clean: Done.
Executing: "D:\Program Files\Microchip\MPASM Suite\MPASMWIN.exe" /q /p18F458 "io.asm" /"io.lst" /e"io.err" /d__DEBUG=1
Executing: "D:\Program Files\Microchip\MPASM Suite\mplink.exe" /p18F458 "io.o" /u_DEBUG /z__MPLAB_BUILD=1 /z__MPLAB_DEBUG=
MPLINK 4.37, Linker
Copyright (c) 1998-2010 Microchip Technology Inc.
Errors      : 0

Loaded D:\bipom\devtools\MPASM\Examples\pic18\io\io.cof.

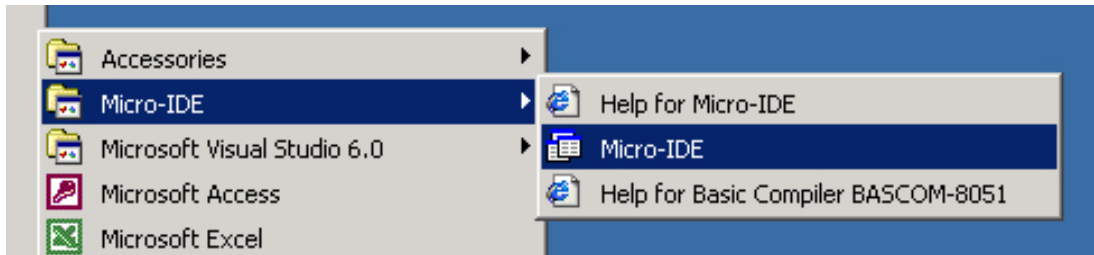
Debug build of project 'D:\bipom\devtools\MPASM\Examples\pic18\io\io.mcp' succeeded.
Language tool versions: MPASMWIN.exe v5.37, mplink.exe v4.37, mplib.exe v4.37
Preprocessor symbol '__DEBUG' is defined.
Sun Sep 19 19:33:02 2010

BUILD SUCCEEDED
```

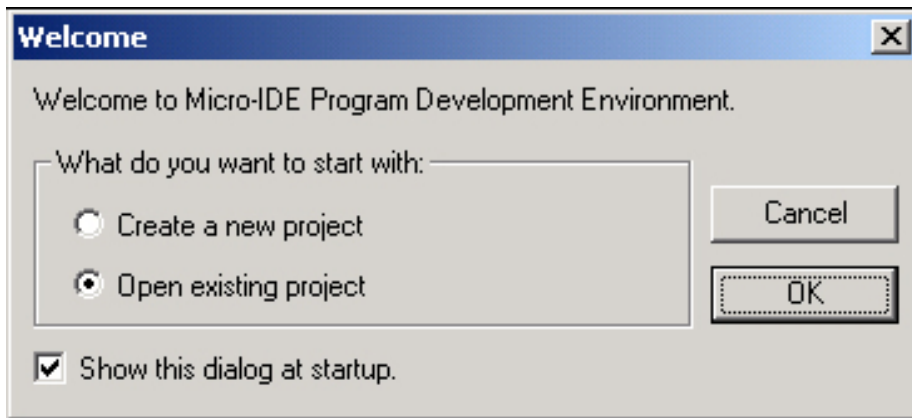
Downloading Programs

To download projects, Micro-IDE is used. We have created project files for both Micro-IDE and MPLAB for all the PIC® examples. The code can be developed and simulated in MPLAB and downloaded to the actual hardware using Micro-IDE. Micro-IDE also has a terminal emulator window that allows monitoring the RS232 serial output from the MINI-MAX/P18 board.

Start Micro-IDE by selecting Start, Programs and Micro-IDE. Select the Micro-IDE option under Micro-IDE folder. This will start Micro-IDE.



When Micro-IDE is started, the Project selection window appears:



Click Cancel for this first time because you will first configure communications before opening a project.

After you have started Micro-IDE, configure the correct COM port and communications parameters:

1. Select Tools and Options from the Micro-IDE menu.
2. Under Terminal tab, make sure Com Port is selected as the port that you connected to the MINI-MAX/P18 board. For example, if the board is connected to COM1, select COM1 under Terminal tab. Make sure that the Terminal options are set as follows:

Baud Rate: 19200
Data Bits: 8
Stop Bits: 1
Parity: None
Echo: Off

3. Under Loader tab, make sure Com Port is selected as the port that you connected MINI-MAX/P18 board. For example, if the board is connected to COM1, select COM1 under Loader tab. Make sure that the Loader options are set as follows:

Baud Rate: 19200
Data Bits: 8
Stop Bits: 1
Parity: None
Echo: Off

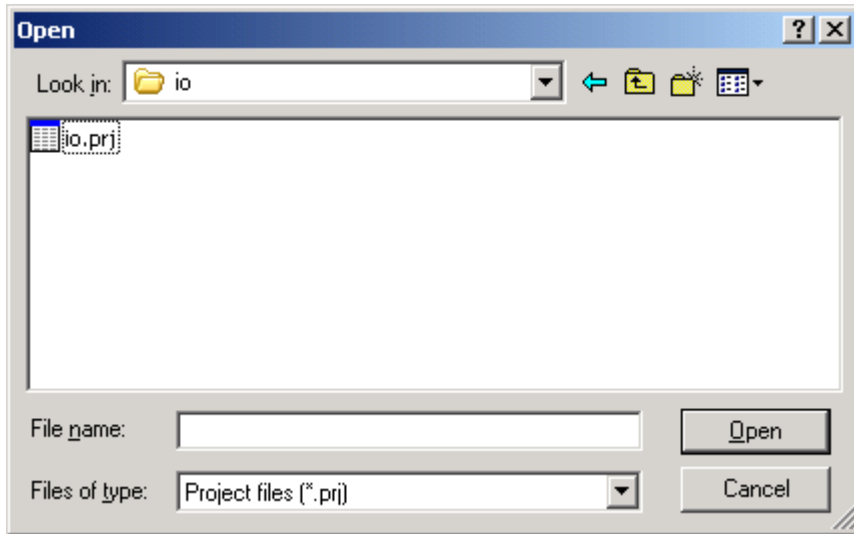
4. Open the Terminal window by selecting Terminal under View menu. A blank terminal screen will appear on the right side of the Micro-IDE window. (You can resize the terminal screen by selecting the left edge of the terminal window with the left mouse button and dragging to the right.).

5. Check communications to the MicroTRAK. Start the Terminal program by selecting Terminal under View menu. A blank terminal screen will appear on the right side of the Micro-IDE window. (You can resize the terminal screen by selecting the left edge of the terminal window with the left mouse button and dragging to the right.)

6. Select Tools, Terminal and Connect. This will open the COM port and connect the terminal to the MINI-MAX/P18.
Make sure the MINI-MAX/P18 board is powered and connected to the PC as described in the section **Installing the Hardware**.

Open the *io.prj* project that is under:

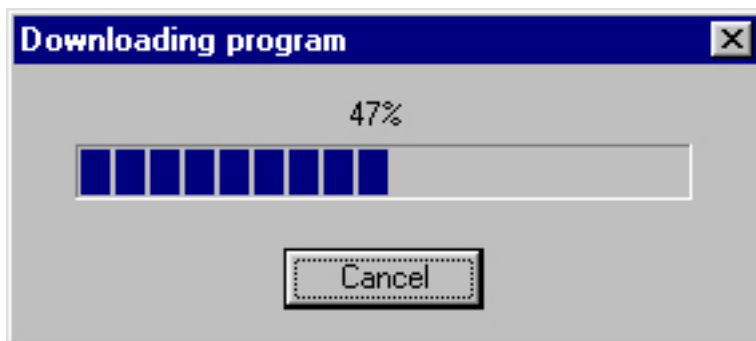
\\bipom\devtools\MPASM\Examples\pic18



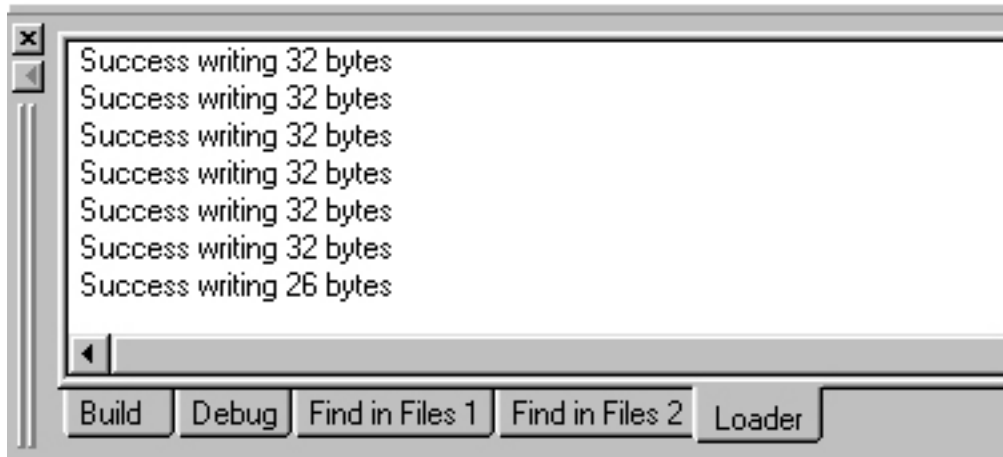
Download the file to the board by selecting Download under Build menu:



If the board is powered and connected properly to the PC, a progress dialog will appear:



The progress dialog will disappear following a successful download. Details of the download are shown on the Output Window:



When the download is finished, the progress indicator disappears. This means that the board has received the program successfully.

After the program has been successful downloaded, it can be started using the Mode button on the main Toolbar:



Mode button puts the board into **Run** or **Program** mode. In Run mode, the micro-controller is executing the program in its memory. In Program mode, the micro-controller is in Reset state so no programs are running. In Program mode, micro-controller's flash memory can be changed and a new program can be downloaded.

The Mode button is Red in Program mode and Green in Run mode. Following a download, the Mode button will be Red. Click the Mode button to change the mode to Run mode. The program **io.hex** that you just downloaded starts executing.

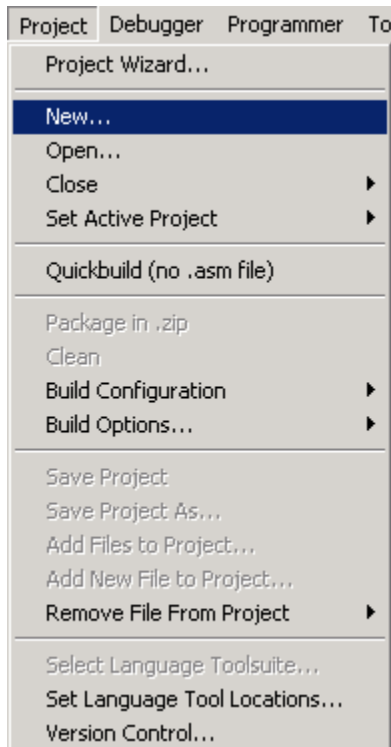
The program **io.hex** will blink the LED's that are connected to PORT D on MicroTRAK's I/O Module.

Congratulations!!! You have built and executed your first program on MicroTRAK.

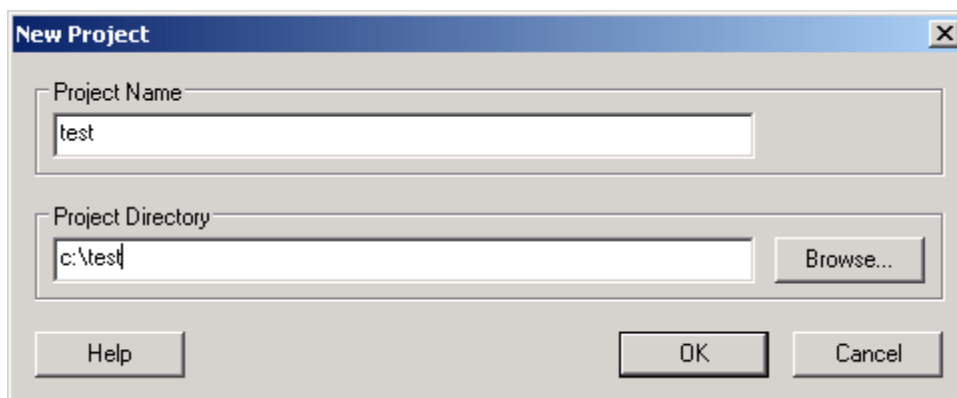
Click the Mode button once again so it turns Red. The board is in Program mode now and it will stop running and the LED's will not blink any more.

Creating Projects

To create your own project, start MPLAB. Select Project->New:

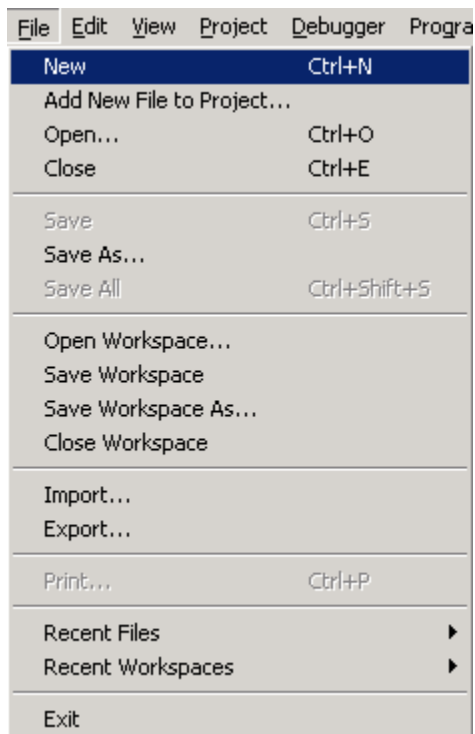


Specify project name and location:

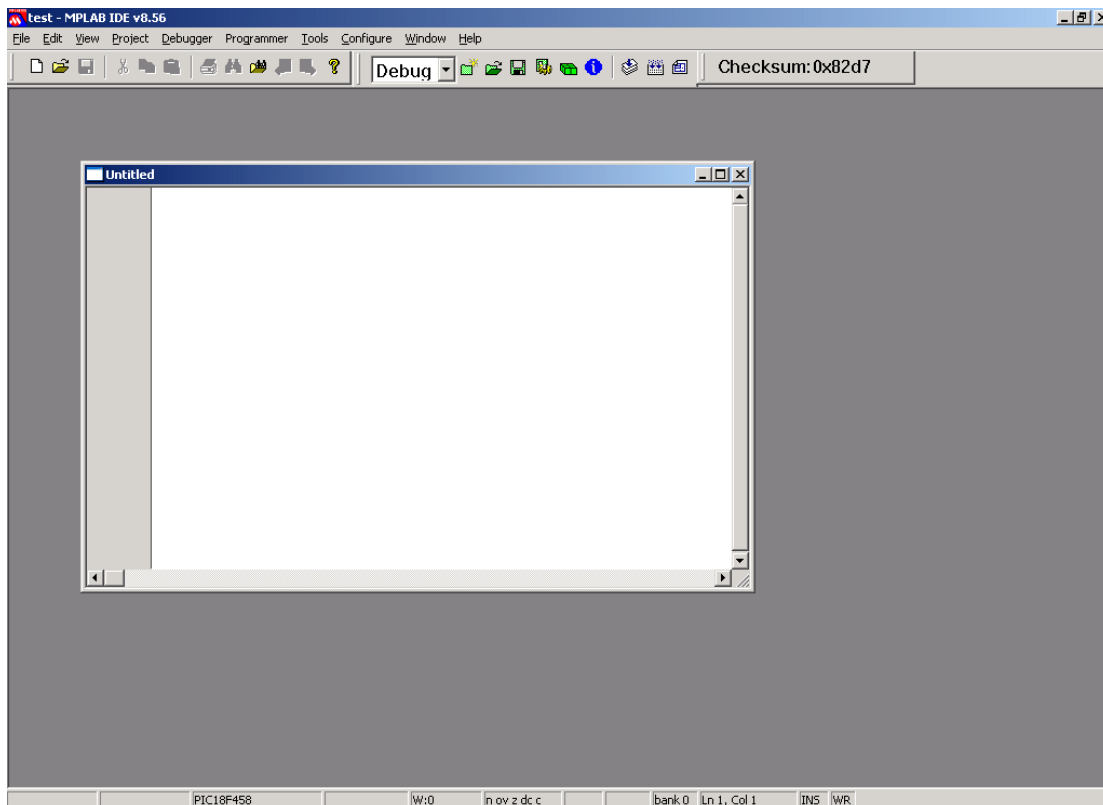


Click OK.

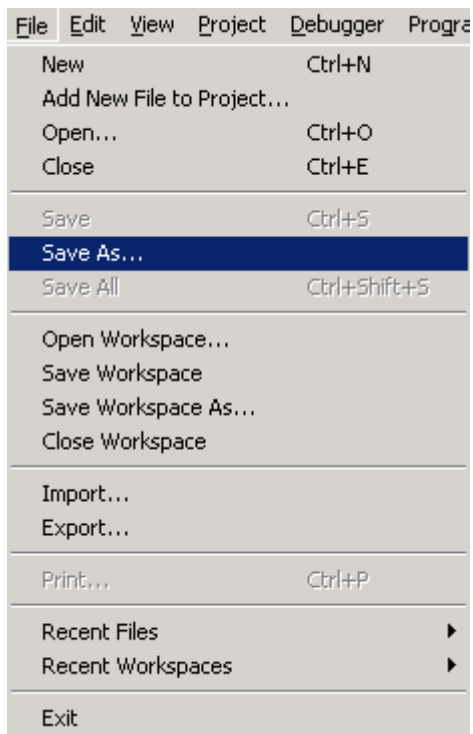
Create a new file by selecting File->New:



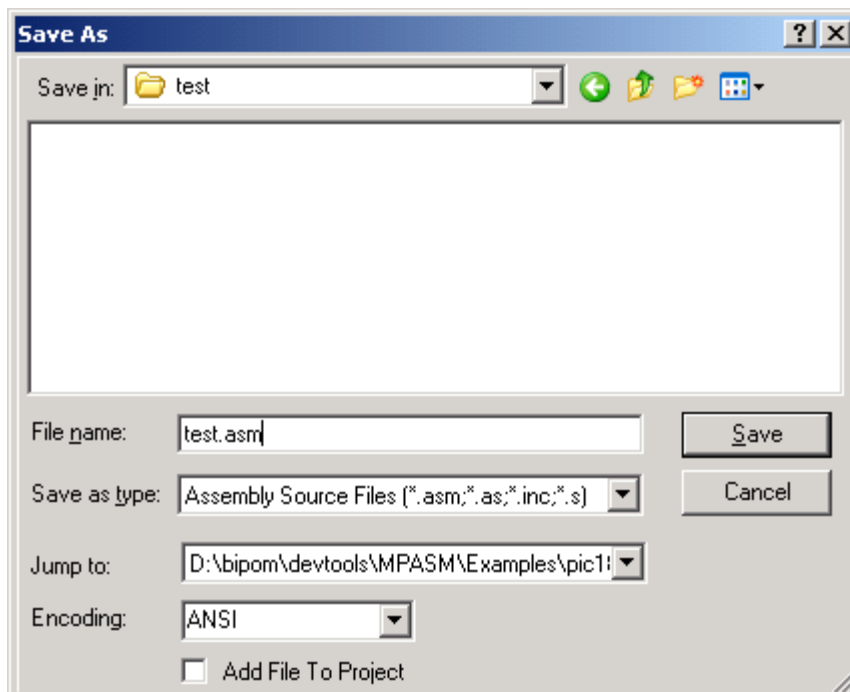
MPLAB will open a new window and show the empty file:



Select File->Save As:

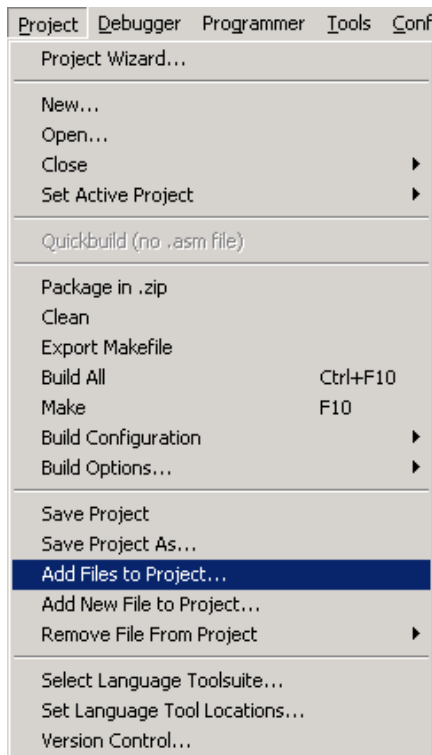


Save the file as **test.asm** to c:\test folder:

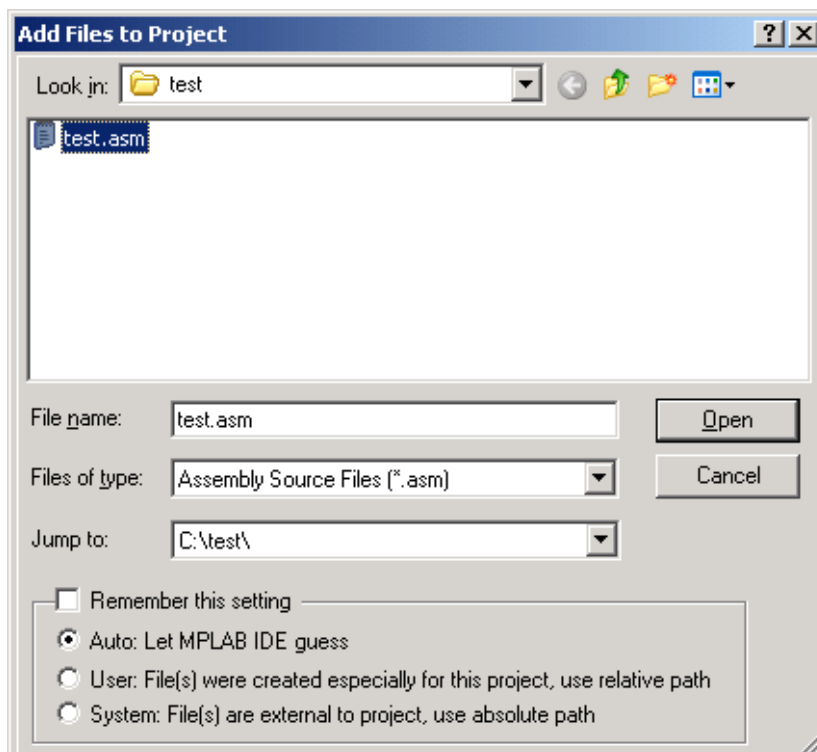


Click Save.

Now add this new file **test.asm** to the test project. Select Project->Add Files to Project:



Select test.asm from c:\test to add to the project:



Click Open.

In the test.asm source file window, type the following to configure the program for PIC18F458 microcontroller:

```
list    p=18f458
```

```
#include <p18F458.inc>
```

```
CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF , STVR = ON
```

Note: When typing, put a tab character before each line in the assembler. Otherwise you may get warnings from the assembler.

list command specifies the microcontroller type as PIC18F458

#include defines the include file to include in this project. In this case, we use the include file p18F458.inc that contains the PIC18F458 specific register names and definitions.

CONFIG command specifies the special hardware configuration values for PIC18F458. In this case:

OSC = HS (this means, we selected high speed crystal as the clock source)

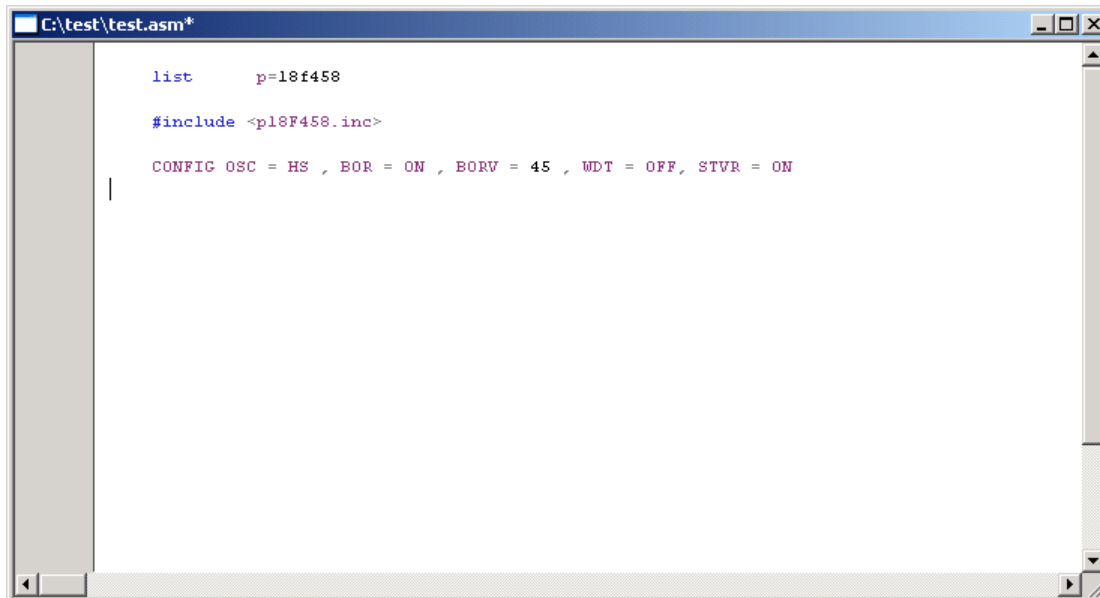
BOR = ON (this means that Brownout detect feature is enabled)

BORV = 45 (this means that the Brownout value is set at 4.5 Volts, supply voltages below 4.5 Volts will results in microcontroller reset)

WDT = OFF (Watchdog timer is disabled)

STVR = ON (A stack overflow will reset the PIC18F458)

The resulting source file window will look like this:



The screenshot shows a text editor window titled "C:\test\test.asm*". The window contains the following assembly code:

```
list    p=18f458

#include <p18F458.inc>

CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF , STVR = ON
```

Now type the following small assembly language program:

```
movlw b'00000000'  
movwf TRISC
```

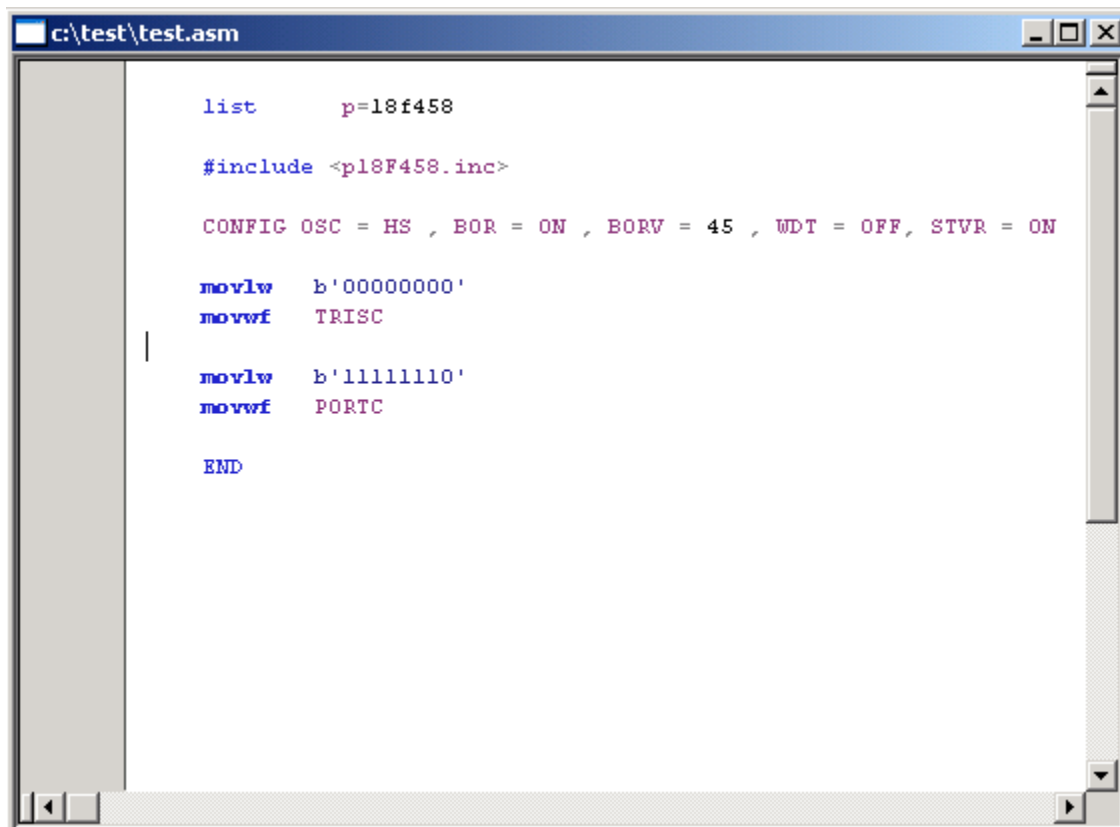
```
movlw b'11111111'  
movwf PORTC
```

b is the symbol for binary notation. For example, **b'11111110'** is the equivalent of **254** decimal or **FE** hex.

TRISC is the data direction register for I/O PORT C. **PORTC** is the data register for I/O PORT C.

This simple program sets first bit of PORT C (also referred to as RC0) as an output and then clears this bit.

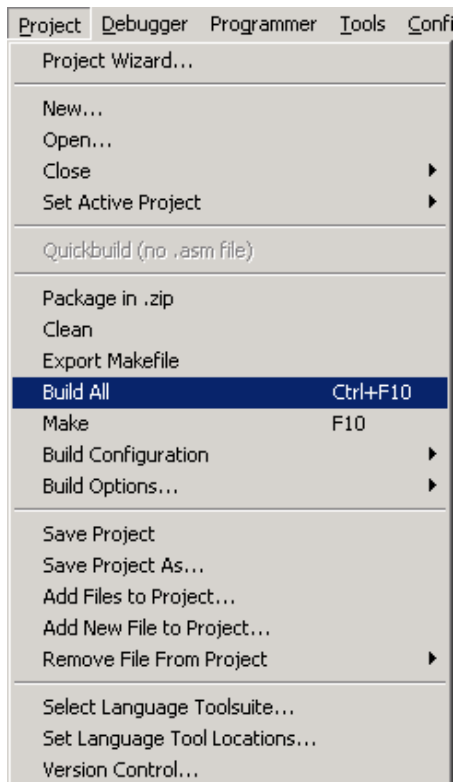
Finally, add the keyword **END** at the end of your program to tell the assembler where the program ends. The resulting source file will look like this:



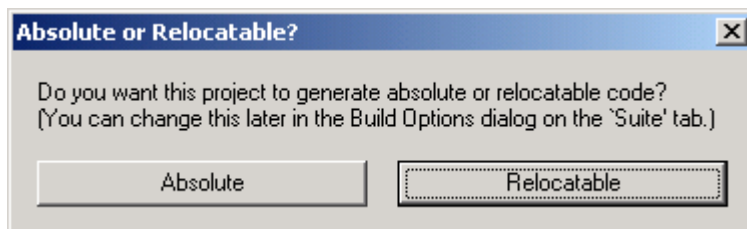
```
c:\test\test.asm  
  
list      p=18f458  
  
#include <p18F458.inc>  
  
CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF , STVR = ON  
  
movlw    b'00000000'  
movwf    TRISC  
  
movlw    b'11111110'  
movwf    PORTC  
  
END
```

Save the file by selecting File->Save.

The next step is to build the project. Select Project->Build All:

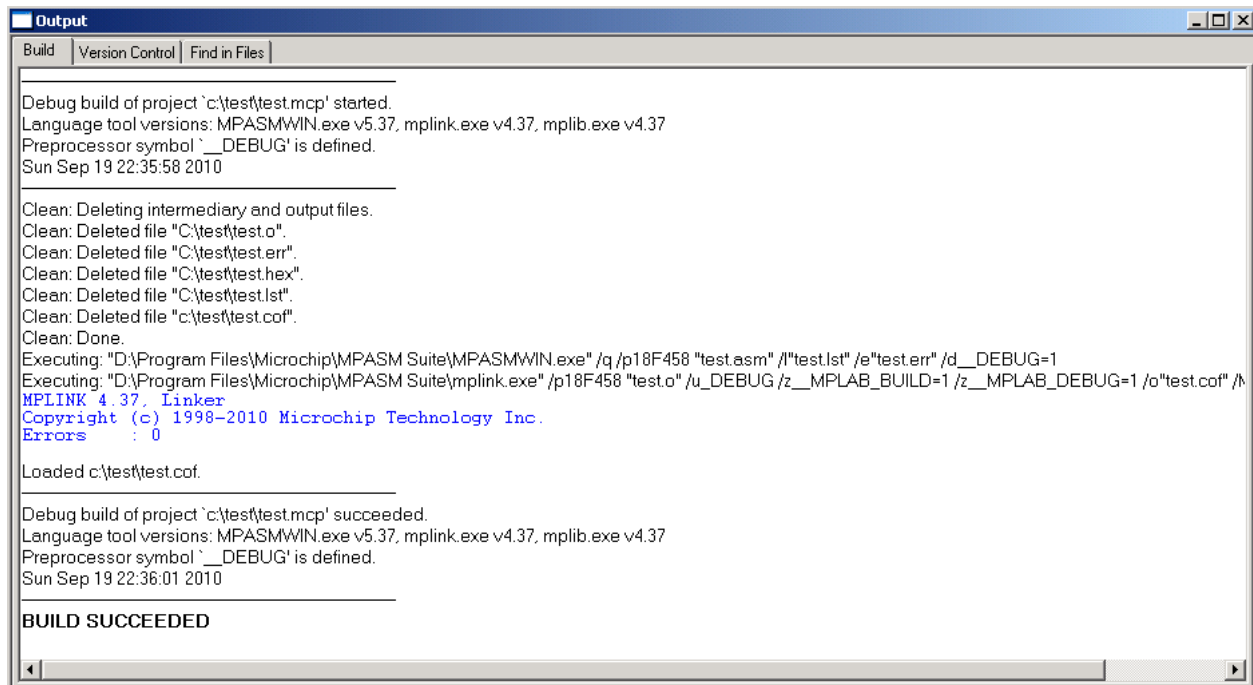


On the first build, MPLAB will prompt with the following question:



Select Absolute.

MPLAB will open the Build Window and build the project successfully if the source file was typed correctly:



```
Output
Build | Version Control | Find in Files

Debug build of project 'c:\test\test.mcp' started.
Language tool versions: MPASMWIN.exe v5.37, mplink.exe v4.37, mplib.exe v4.37
Preprocessor symbol '__DEBUG' is defined.
Sun Sep 19 22:35:58 2010

Clean: Deleting intermediary and output files.
Clean: Deleted file "C:\test\test.o".
Clean: Deleted file "C:\test\test.err".
Clean: Deleted file "C:\test\test.hex".
Clean: Deleted file "C:\test\test.lst".
Clean: Deleted file "c:\test\test.cof".
Clean: Done.
Executing: "D:\Program Files\Microchip\MPASM Suite\MPASMWIN.exe" /q /p18F458 "test.asm" /l"test.lst" /e"test.err" /d__DEBUG=1
Executing: "D:\Program Files\Microchip\MPASM Suite\mplink.exe" /p18F458 "test.o" /u_DEBUG /z__MPLAB_BUILD=1 /z__MPLAB_DEBUG=1 /o"test.cof" /M
MPLINK 4.37, Linker
Copyright (c) 1998-2010 Microchip Technology Inc.
Errors : 0

Loaded c:\test\test.cof.

Debug build of project 'c:\test\test.mcp' succeeded.
Language tool versions: MPASMWIN.exe v5.37, mplink.exe v4.37, mplib.exe v4.37
Preprocessor symbol '__DEBUG' is defined.
Sun Sep 19 22:36:01 2010

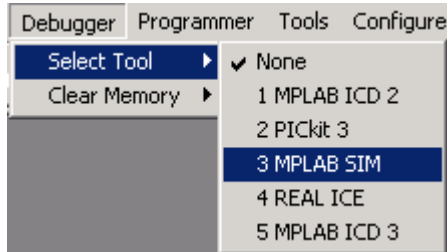
BUILD SUCCEEDED
```

The successful build generates several files, including **test.hex** which is the output file that will be downloaded to the MINI-MAX/P18 board.

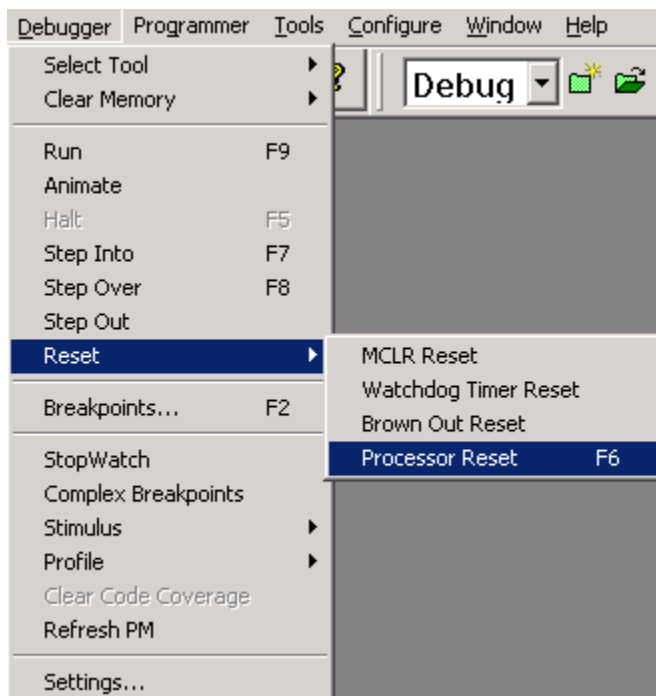
Simulation

You can simulate the micro-controller and single-step through your program without actually having the MINI-MAX/P18 connected to your PC. MPLAB has a built-in PIC® microcontroller simulator

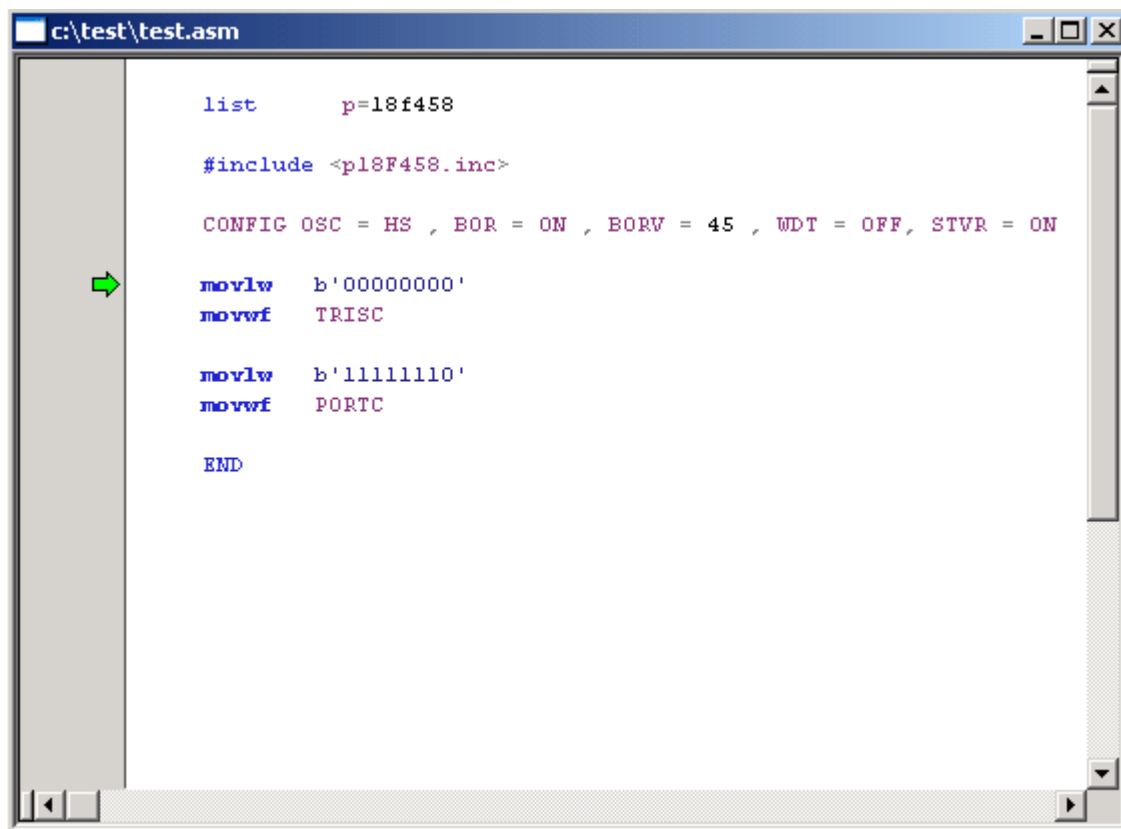
To start the simulation, first specify the simulator/debugger to use by selecting Debugger->Select Tool->MPLAB SIM. MPLAB SIM is the simulator that is built-in to MPLAB.



We will start the simulation by resetting the 18F458 microcontroller (in simulation mode). Select Debugger->Reset->Processor Reset:



This will reset the simulated microcontroller and place the current program position indicator (Program Counter) on the first executable line of code:



```
c:\test\test.asm

list      p=18f458

#include <p18F458.inc>

CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF , STVR = ON

movlw    b'00000000'
movwf    TRISC

movlw    b'11111110'
movwf    PORTC

END
```

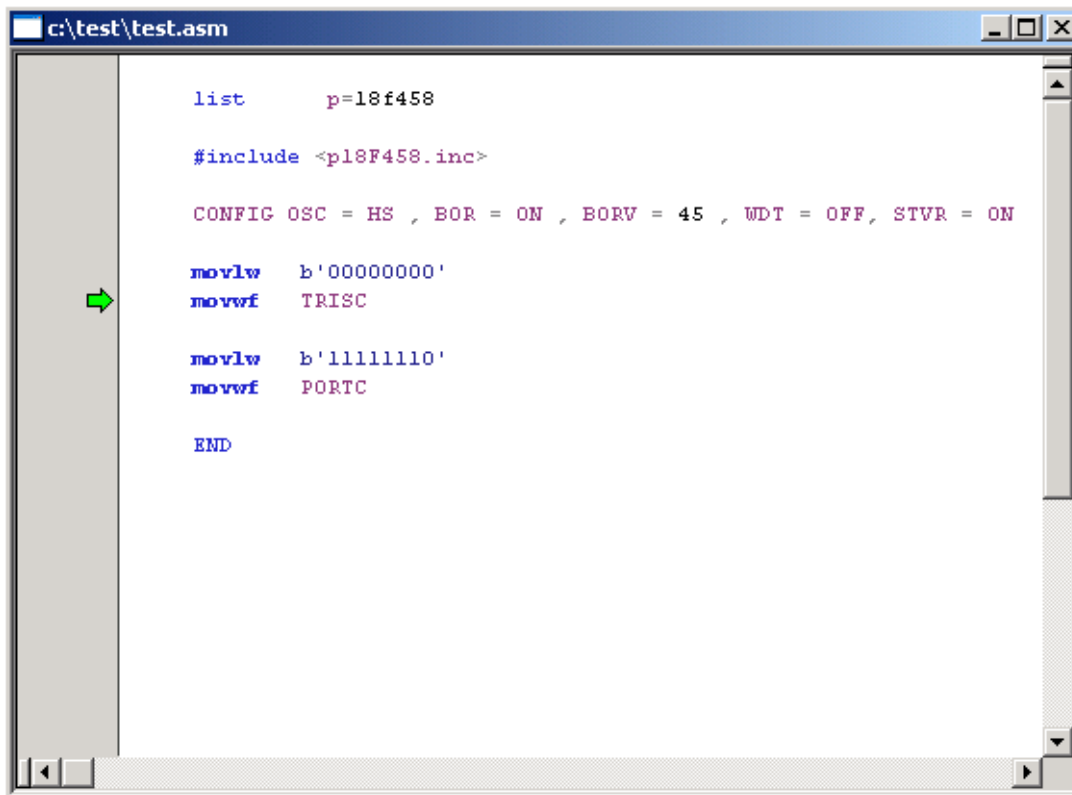
The green arrow shows the current instruction that is about to be executed.

Selecting the Debugger menu, you will notice that there are keyboard shortcuts for Simulator operations:

- F7 for Step Into
- F8 for Step Over
- F9 for Run
- F2 for Breakpoints

These keyboard shortcuts are faster and easier to use than menu operations and are recommended.

Press F7 and the green arrow will move to the next executable instruction:



```
list      p=18f458

#include <p18F458.inc>

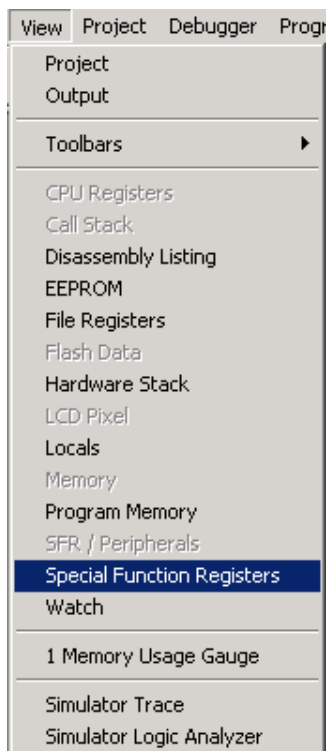
CONFIG OSC = HS , BOR = ON , BORV = 45 , WDT = OFF , STVR = ON

movlw    b'00000000'
movwf    TRISC

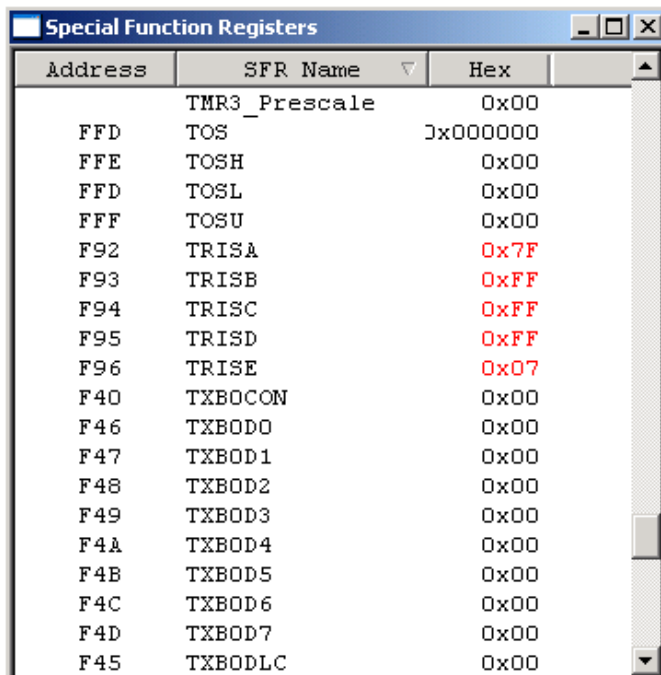
movlw    b'11111110'
movwf    PORTC

END
```

To view the simulated PIC18F458 registers, select View->Special Function Registers:



Special Function Registers window will appear:



Address	SFR Name	Hex
	TMR3_Prescale	0x00
FFD	TOS	0x000000
FFE	TOSH	0x00
FFD	TOSL	0x00
FFF	TOSU	0x00
F92	TRISA	0x7F
F93	TRISB	0xFF
F94	TRISC	0xFF
F95	TRISD	0xFF
F96	TRISE	0x07
F40	TXBOCON	0x00
F46	TXBOD0	0x00
F47	TXBOD1	0x00
F48	TXBOD2	0x00
F49	TXBOD3	0x00
F4A	TXBOD4	0x00
F4B	TXBOD5	0x00
F4C	TXBOD6	0x00
F4D	TXBOD7	0x00
F45	TXBODLC	0x00

Click on **SFR Name** column to sort by SFR name. Scroll to TRISC. The value of TRISC is now FF hex. This is the default value upon reset.

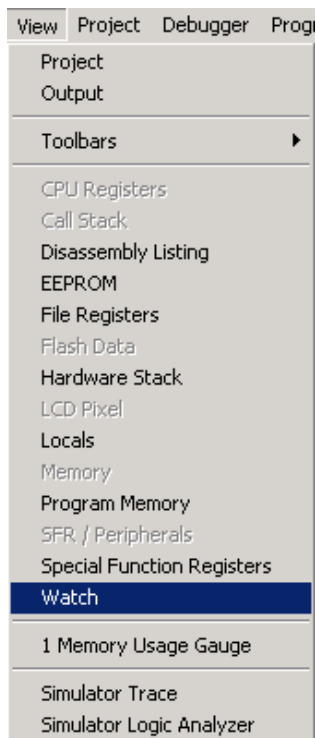
Press F7 to step one more instruction. This will cause the instruction

```
movwf TRISC
```

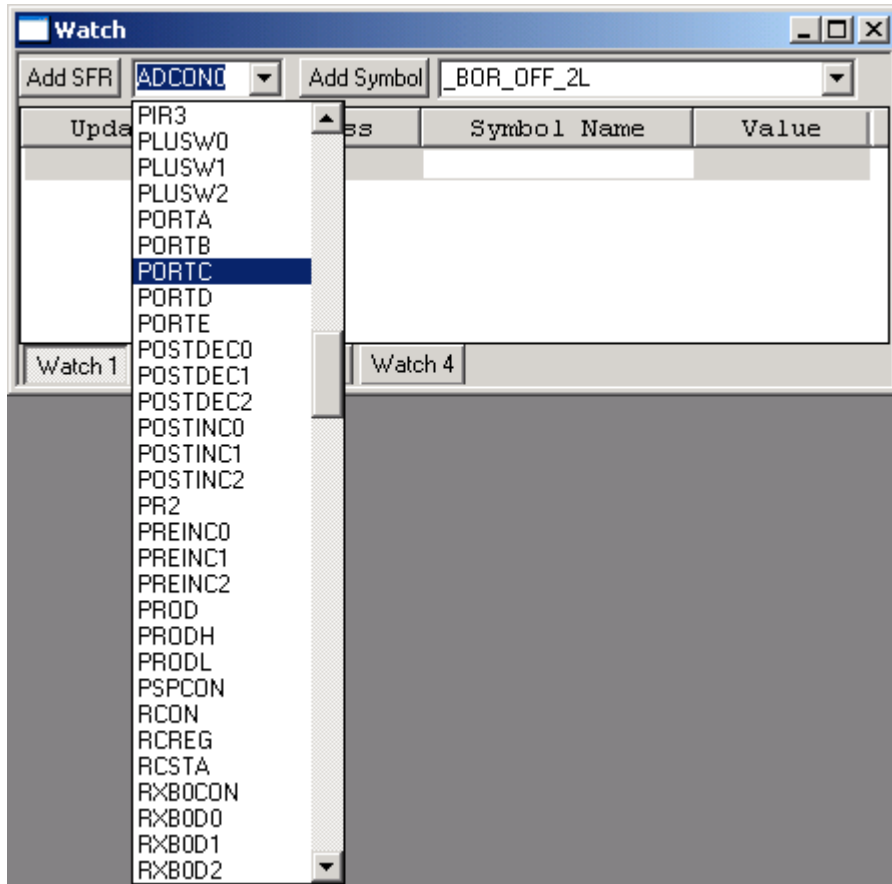
to execute and this instruction will assign the value of W (Accumulator) to TRISC. Since W was assigned a value of b'11111110' (FE hex), TRISC will now have this value. The new value of TRISC is updated and shown in the Special Function Registers window:

Address	SFR Name	Hex
	TMR3_Prescale	0x00
FFD	TOS	0x000000
FFE	TOSH	0x00
FFD	TOSL	0x00
FFF	TOSU	0x00
F92	TRISA	0x7F
F93	TRISB	0xFF
F94	TRISC	0xFE
F95	TRISD	0xFF
F96	TRISE	0x07
F40	TXBOCON	0x00
F46	TXBOD0	0x00
F47	TXBOD1	0x00
F48	TXBOD2	0x00
F49	TXBOD3	0x00
F4A	TXBOD4	0x00
F4B	TXBOD5	0x00
F4C	TXBOD6	0x00
F4D	TXBOD7	0x00
F45	TXBODLC	0x00

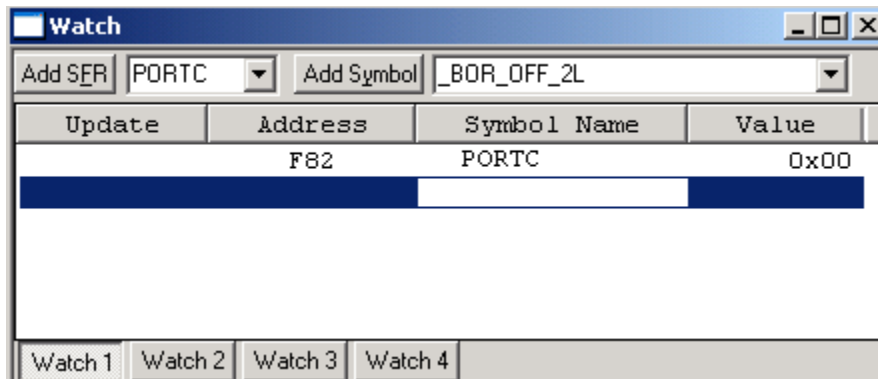
Another convenient method of watching variables and special function registers is to use the Watch window. Select View->Watch:



This will open Watch window. Select the Special Function Register to be watched from the left pull down list. In this case, we are using PORTC in our program so we can watch the value of PORTC:



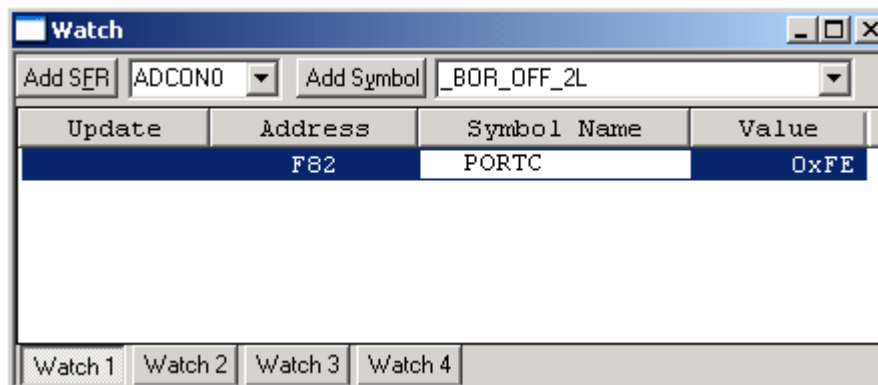
After selecting PORTC, click the Add SFR button. PORTC will be added to the list of variables to be watched and its current value will be displayed:



Press F7 twice to single step over the lines:

```
movlw b'11111110'  
movwf PORTC
```

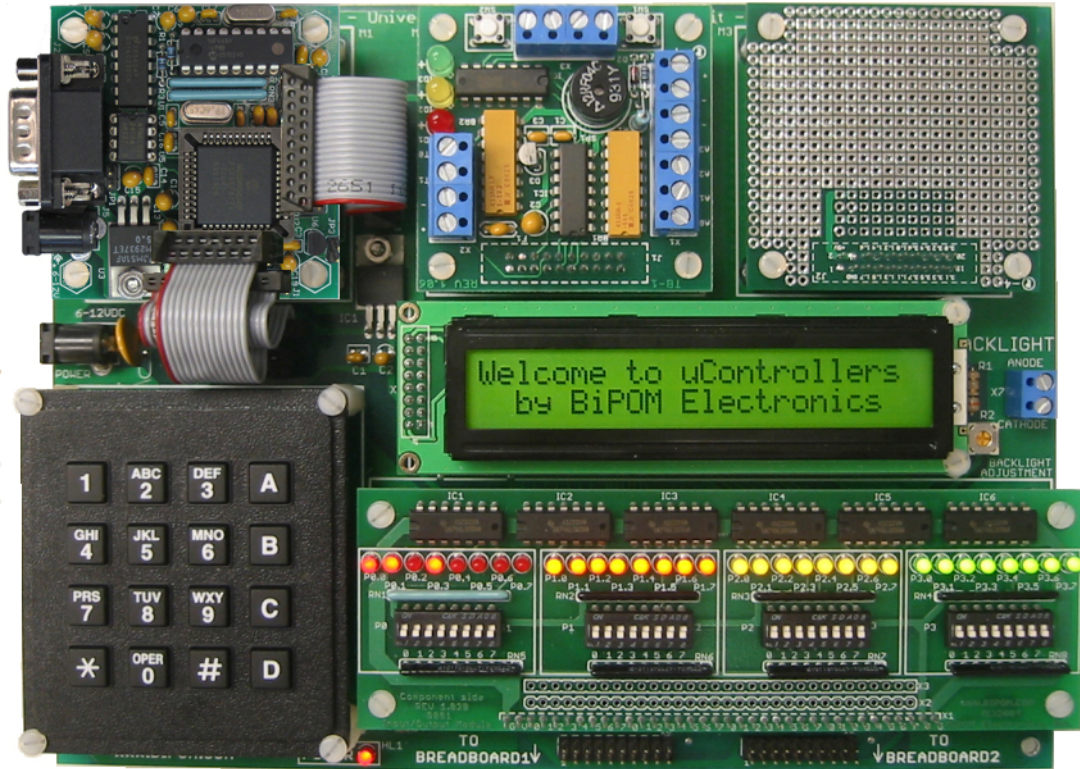
The value of PORTC will change from to FE hex:



MicroTRAK/P18 Complete Carrier Board

Overview

MicroTRAK/P18 Complete includes MicroTRAK Carrier Board, MINI-MAX/P18 Microcontroller Board, TB-1 Training Board, PROTO-1 Prototyping Board, I/O Module for PIC®, LCD242 LCD, KP1-4X4 Keypad, Cables, Adapter, Training Manuals, Labbook, Micro-IDE, example projects, MPLAB with Assembler, Debugger and Simulator (free download from Microchip®), Serial downloader.



MicroTRAK carrier board has the following configuration:

- Sockets for a microcontroller board
- Sockets for dual peripheral boards
- Keypad interface
- Industry-standard display interface for alphanumeric LCD and VFD displays.
- Connectors and cables for connection to a standard breadboard
- Expansion port for a microcontroller-specific pluggable I/O module with port connectors, port indicator LED's and port control DIP Switches.
- Configuration of the high speed input via 3 jumpers.
- Single operating unregulated voltage 6 ... 12VDC
- On-board 5 Volt regulator
- Dimensions are 8.8 X 6.7 inches (22.4 X 17.0 centimeters).
- Mounting holes of 0.15 inches (3.8 millimeters) are on four corners.
- 0° - 70° C operating, -40° - +85° C storage temperature range.

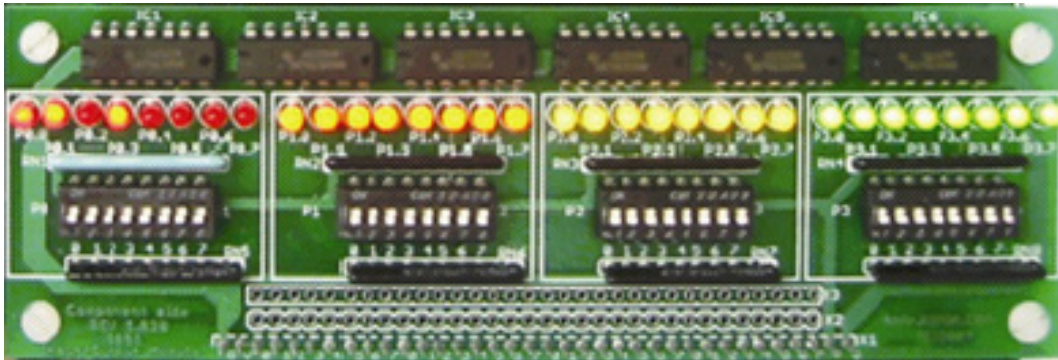
I/O Module

Overview

I/O Module is a highly useful part of MicroTRAK training kit system for use with MINI-MAX/P18 Single Board Computers (SBC). MicroTRAK is the ultimate training kit and project development platform with microcontrollers.

I/O Module allows access to all input/output (I/O) ports of the PIC18F458 micro-controller on the MicroTRAK development platform. I/O Module has 32 switches to control the PIC18F458 microcontroller inputs and 32 LED's to indicate the port statuses as logic LOW or logic HIGH.

I/O Module is powered from a 5 Volt regulated DC power source through the 36-pin input/output connector.



I/O Module has the following configuration:

- . 36-pin pluggable module connector
- . Two 32-pin expansion connector footprints (for soldering of wires or connectors by the user)
- . 32 DIP switches to control the PIC18F458 micro-controller inputs
- . 32 port indicator LED's with 74ALS05 hex inverters as drivers
- . Requires regulated 5VDC supply at 250mA maximum current (when all LED's are on)
- . Dimensions are 5.95 X 1.975 inches (15.1 X 5.0 centimeters).
- . Mounting holes of 0.15 inches (3.8 millimeters) are on four corners.
- . 0° - 70° C operating, -40° - +85° C storage temperature range.

MINI-MAX/P18 Micro-controller Board

Overview

MINI-MAX/P18 is a general purpose, low-cost, highly reliable, and highly expandable micro-controller system. It is based on the Microchip Technology PIC18F458 single-chip Flash micro-controller. This microcontroller features

- 32K In-System Re-programmable Downloadable Flash Memory
- 1.5K RAM
- 256 bytes of EEPROM data memory
- 15 Interrupt Sources
- Two 8-bit Timers / counters with prescalers
- One 16-bit timer / counter
- Two 16-bit compare / capture PWM modules
- 10-bit 8-channel ADC
- Two analog comparators
- Programmable UART Serial Channel
- SPI and Master I2C Serial Interfaces
- Controller Area Network (CAN) Bus
- Programmable Watchdog Timer
- Brown-out detector
- 33 general purpose I/O pins

MINI-MAX/P18 board complements these features by providing

- 512-byte EEPROM (optional 128-Kilobyte EEPROM)
- RS232 Serial Port
- In-circuit Programming of the micro-controller through the serial port
- Precision reference voltage source for ADC
- Keypad connector
- LCD connector (with programmable contrast adjustment for LCD)
- Expansion bus interface to low-cost peripheral boards.

MINI-MAX/P18 board also supports PIC16F877A, PIC18F442 and PIC18F452 micro. These devices are pin compatible with the PIC18F458 and can be directly placed into the MINI-MAX/P18 PLCC-44 socket.

MINI-MAX/P18 is a highly reliable system:

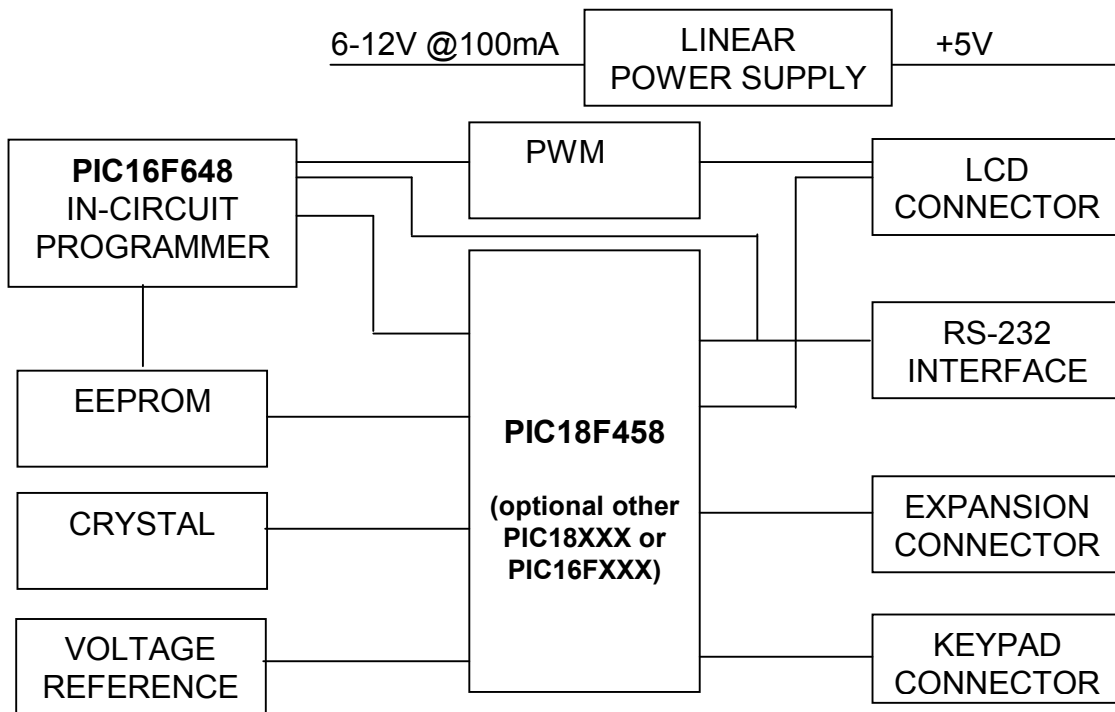
- 2-layer Printed Circuit Board
- Hardware Watchdog timer of PIC18F458 provides protection against software failures and lock-ups.
- PIC16F648 In-System programmer supports Software Watch-Dog timer. Timeout is selectable from 1 to 127 seconds. If this function is activated, the PIC18F458 should communicate with PIC16F648 through I2C bus to prevent RESTART. When PIC18F458 fails to communicate with PIC16F648, the PIC16F648 will generate a RESET signal for PIC18F458.
- PIC16F648 generates reliable RESET signal in power-up and in brownout.

Specifications

Dimensions are 2.35 X 2.40 inches (5.97 X 6.10 centimeters). Mounting holes of 0.125 inches (3 millimeters) on four corners. 0° - 70° C operating, -40° - +85° C storage temperature range.

Functional Blocks

Figure 1 shows block diagram of the MINI-MAX/P18 system



Micro-controller

MINI-MAX/P18 has a Microchip PIC18F458 micro-controller (U2). Micro-controller ports and power lines are provided on a 20-pin Expansion bus (J4) for interfacing to peripherals and other external circuits. PIC18F458 has five ports: 6-bit PORTA, 8-bit PORTB, 8-bit PORTC, 8-bit PORTD and 3-bit PORTE. All of these port pins can be used as general I/O.

Four PORTB lines and three PORTE lines are available on the LCD connector. PORTE lines can be used as analog inputs. Some of PORTA, PORTB and PORTC lines are available on the Expansion connector for general I/O or have special alignments such as asynchronous serial port, interrupt inputs, A/D inputs, and timer inputs. PORTD is available on the keypad connector.

MINI-MAX/P18 has Pulse Width Modulation (PWM) circuit, which can vary LCD contrast. Alternatively it can be used as a low speed analog output.

More information on the PIC18F458 micro-controller can be obtained from Microchip's web site at www.microchip.com.

Using the Analog to Digital converter

PIC18F458 has an 8-channel 10-bit analog to digital converter. It can use on-board +5V power (Vcc) as reference voltage. For best accuracy and noise performance, ADC can be configured to use external reference that is provided on the MINI-MAX/P18 board. It is permanently connected to RA3. Also, for this purpose MINI-MAX/P18 board has separate ground circuit for analog signals. This circuit is RA2 (pin #7 on expansion connector). JP3 jumper should be set to use RA2 as the analog ground. MINI-MAX/P18 board comes with JP3 jumper, already installed at the factory.

EEPROM

MINI-MAX/P18 uses a 24C04 (U5) 512-byte Electrically Erasable Programmable Read-Only-Memory (EEPROM). Typically this EEPROM is used for storing calibration values for sensors, customer identification, serial number and other parameters. This EEPROM is on a socket and can easily be replaced with higher capacity EEPROM's (up to 128 Kilobytes).

In-System Programming

PIC18F458 micro-controller can be re-programmed remotely over the RS-232 interface using a second micro-controller on the board (PIC16F648). The in-circuit programming feature simplifies program development on the board since downloading programs from a host PC takes only few seconds.

[MC Development System](#) based on [Micro-IDE](#) Integrated Development Environment from BiPOM Electronics fully supports in-system programming on the MINI-MAX/P18 board using the serial port. A Windows-based program [WinLoad](#) from BiPOM Electronics is provided to download programs to the MINI-MAX/P18 board.

Also, BiPOM Electronics provides a special piggyback module called [PIGGY](#). Using this module, the user can connect the Microchip MPLAB-ICD to MINI-MAX/P18.

Microchip's In-Circuit Debugger, MPLAB-ICD, is a powerful, low-cost development and evaluation kit for the FLASH PIC16F87XA microcontroller (MCU) family. MPLAB ICD utilizes the In-Circuit Debugging capability of the PIC16F87XA. This feature, along with Microchip's In-Circuit Serial Programming™ (ICSP™) protocol, offers cost-effective in-circuit FLASH programming and debugging from the graphical user interface of the MPLAB Integrated Development Environment (IDE). A designer can develop and debug source code by watching variables, setting break points, and single-stepping. Contact Microchip Technology's Web site at www.microchip.com for information on how to use the MPLAB ICD.

Keypad connector

8 pins of PORTD are connected to the Keypad connector. Many different keypads (for example, 3 by 5 or 4 by 4) can be connected directly to the keypad connector. 5 Volt and Ground power lines are also available on the Keypad connector. This connector can also be used as a general-purpose port.

Keypad Connector (J1)

Signal	Pin
RD0	1
RD1	2
RD2	3
RD3	4
RD4	5
RD5	6
RD6	7
RD7	8
Ground	9
Vcc	10

Table 1.

LCD Connector

This connector is intended for various types of alphanumeric LCD modules. RB0, RB1, RB2, RB4 are the 4-bit data bus, RE0, RE1, RE2 are the control signals. All these lines can be used as general purpose I/O. RE0-RE2 can serve as analog inputs. Vee is a slow analog PWM output to adjust contrast of LCD display. Alternatively, it can be used as a general-purpose analog output.

LCD Connector (J3)

Signal	Pin	Pin	Signal
Ground	1	2	Vcc
Vee	3	4	RE2
RE0	5	6	RE1
N/C	7	8	N/C
N/C	9	10	N/C
RB0	11	12	RB1
RB2	13	14	RB4

Table 2.

Power Supply Unit

MINI-MAX/P18 series boards come with a 6 Volt unregulated DC power supply. Other power supplies can also be used although this invalidates the warranty. External power supply should be able to supply 6 to 12 Volts DC at minimum 100mA current. The inner pin of the power supply connector is positive and the outer ring is negative.

WARNING: Correct polarity should be observed when applying external DC supply to Power terminal; otherwise MINI-MAX/P18 will be permanently damaged.

MINI-MAX/P18 has an on-board 5 Volt regulator (U3).

CAUTION: Depending on the current requirements of the any external circuitry such as peripheral boards that are attached to MINI-MAX/P18 and the level of input voltage applied, the power regulator U3 may dissipate enough heat to cause skin injury upon touch. Contact with this regulator should be avoided at all times, even after the power to circuit has been switched off.

Asynchronous Serial Port

One asynchronous RS232 serial port (J2) is available on MINI-MAX/P18.

U1 converts micro-controller's RXD and TXD pins to/from RS232 levels. U1 has built-in voltage-doubler and inverter that generates +/- 10 Volts for RS232 logic levels. RS232 port is made available on a 9-pin male D connector J2. Hand-held terminals, computers, modems and other serial devices may be connected to the RS232 port. CTS/RTS Modem control lines are provided on the RS232 port. CTS is used by external host such as a PC to put MINI-MAX/P18 in program or run modes. Therefore, user applications must not use CTS line.

RS232 Serial Port (J2)

Signal	Pin
Not Connected	1
Receive (RXD)	2
Transmit (TXD)	3
Not Connected	4
Ground	5
Not Connected	6
RTS	7
CTS	8
Not Connected	9

Table 3

Many users try to use HyperTerminal to send some data bytes to a MINI-MAX/P18 board. HyperTerminal forces a board to PROGRAM MODE by RTS line. PIC programs can not be executed if HyperTerminal occupies the RS-232 port. We advise to use Micro-IDE terminal window instead of HyperTerminal.

Expansion

Most of the micro-controller pins and the 5-Volt power supply lines are available on the 20-pin MINI-MAX/P18 Expansion connector (J4) for interfacing to external circuitry, prototyping boards and peripheral boards. MINI-MAX/P18 peripheral boards can be connected either as a piggyback daughter-board on MINI-MAX/P18 using standoffs or can be placed up away from MINI-MAX/P18 using a 20-wire ribbon cable. Peripherals section lists the available expansion boards. Table 4 shows the pin assignments for the MINI-MAX/P18 Expansion connector.

MINI-MAX/P18 Expansion (J4)

Signal	Pin	Pin	Signal
RC7	20	19	RC6
RB6	18	17	RB3
RC1	16	15	RA4
RC0	14	13	RA5
RB7	12	11	RC2
RA0	10	9	RA1
RC5	8	7	RA2
RC3	6	5	RC4
VCC	4	3	GND
VCC	2	1	GND

Table 4

Peripherals

MINI-MAX/P18 can be connected to a wide variety of low-cost peripheral boards to enhance its functionality. Some possibilities are:

- Prototyping board (PROTO-1)
- Training Board (TB-1)
- 4-digit 7-segment LED display board
- 12-bit Analog-To-Digital Converter Board
- Digital Input/Output Expander Board
- Real time clock + 128 MB flash card board
- Terminal board
- Reed relay board with 4 relays
- Power relay board with 2 relay
- Stepper motor driver board

Peripheral boards can either be stacked on top of MINI-MAX/P18 using stand-offs or connected in a chain configuration using flat ribbon cable. Figure 2 shows how MINI-MAX/P18 can be connected to a peripheral board in a stacked fashion. Figure 3 shows chain connection.

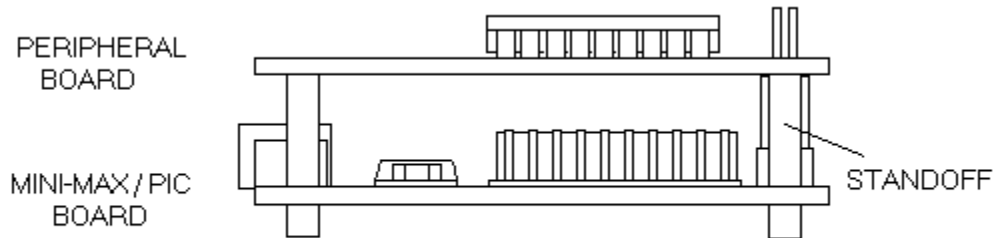


Figure 2

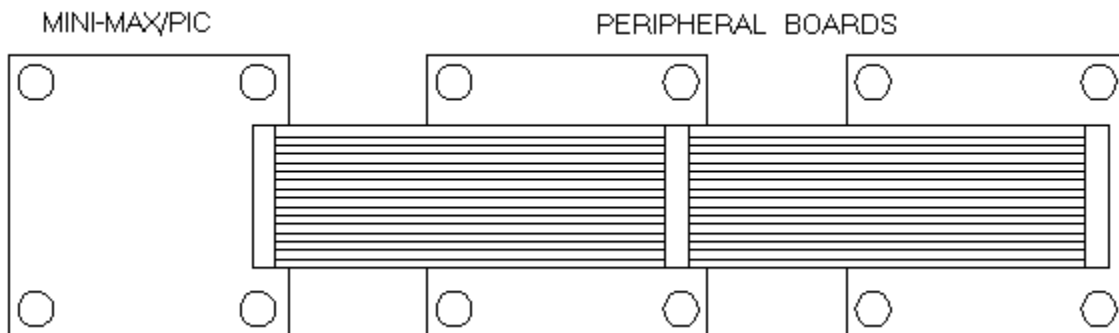


Figure 3

More details concerning BiPOM Peripheral boards are available from the link below:

www.bipom.com/peripherals.php

RS232 Devices

Various keypads and terminals may be connected to the RS232 port of MINI-MAX/P18 through connector J2. MINI-MAX/P18 can be connected to a host PC through the RS232 port. For example, MINI-MAX/P18 can be used as a remote data acquisition or control unit serving a host PC in a client-server configuration.

Connection to a host PC is accomplished by using a NULL-Modem cable. MINI-MAX/P18 end of this cable should be a 9-pin Female D connector for connection to J2 on the MINI-MAX/P18 board. Host PC end of this cable can be either 9-pin Female or 25-pin Female D Connector depending on available serial (COM) ports on the host PC.

MINI-MAX/P18 board comes with a NULL modem (LapLink) cable that has the following wiring connections:

MINI-MAX/P18 9-pin Female			Host PC 9-pin Female
RECEIVE DATA (RXD)	2	3	TRANSMIT DATA (TXD)
TRANSMIT DATA (TXD)	3	2	RECEIVE DATA (RXD)
GROUND	5	5	GROUND
RTS	7	8	CTS
CTS	8	7	RTS

MINI-MAX/P18 9-pin Female			Host PC 25-pin Female
RECEIVE DATA (RXD)	2	2	TRANSMIT DATA (TXD)
TRANSMIT DATA (TXD)	3	3	RECEIVE DATA (RXD)
GROUND	5	7	GROUND
RTS	7	5	CTS
CTS	8	4	RTS

Table 5

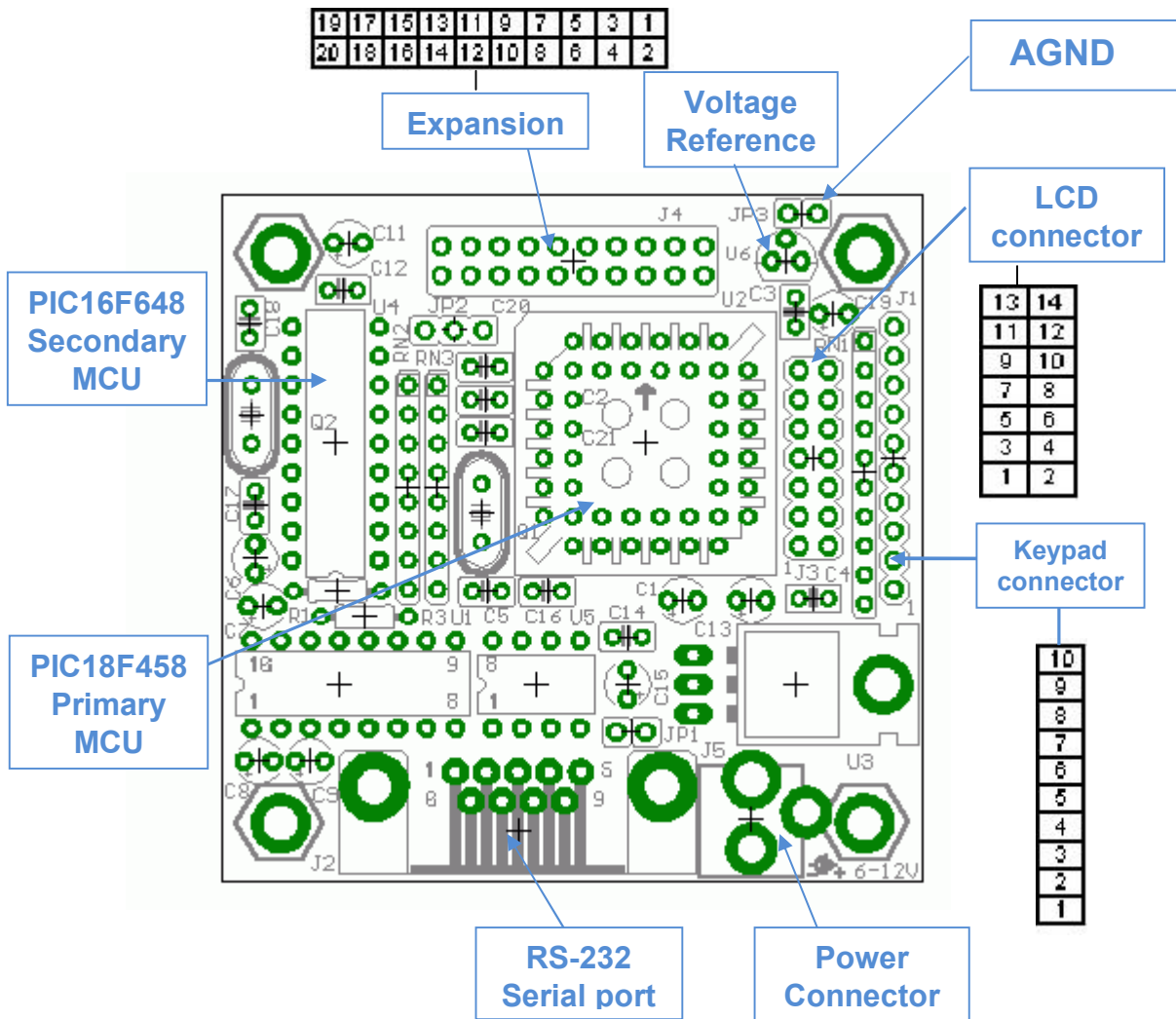
Software

MPASM development system provides a lot of examples for the MINI-MAX/P18 board to access on-board peripherals and perform self-diagnostics.

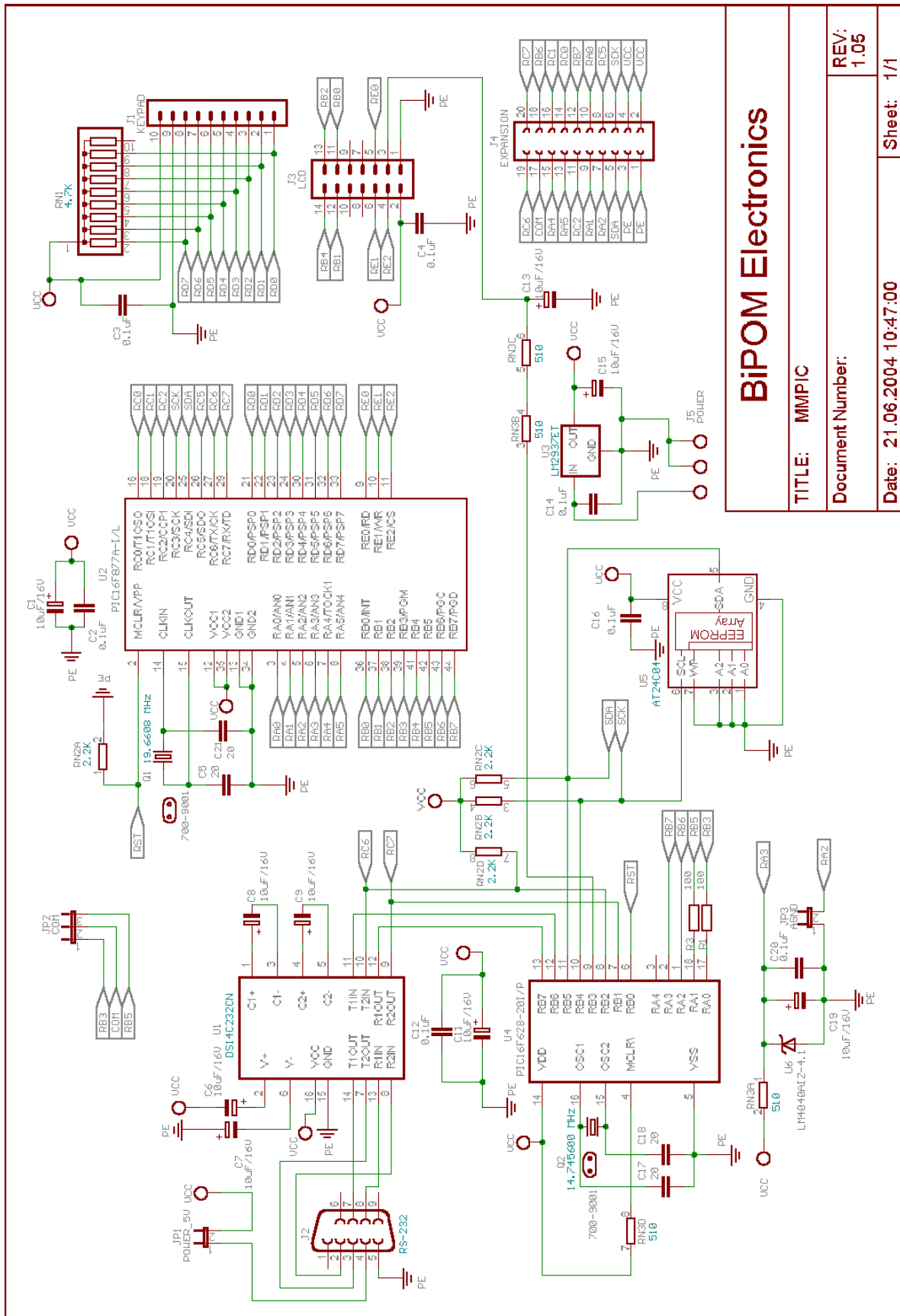
Please download the development system from www.bipom.com/mmpicsoft.php

Also, WinLoad Windows Loader is available to download program codes to the MINI-MAX/P18:

Board Layout



Schematics



BiPOM Electronics

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TB-1 TRAINING BOARD

Overview

Training Board TB-1 allows performing various experiments with most microcontrollers. TB-1 features:

- 3 Traffic light LED's (red, yellow, green)
- 2 interrupt inputs
- 2 switch inputs (in parallel with interrupt inputs)
- 2 timer/counter inputs
- 4 channels of 8-bit analog inputs
- Programmable buzzer
- Expansion bus to other boards

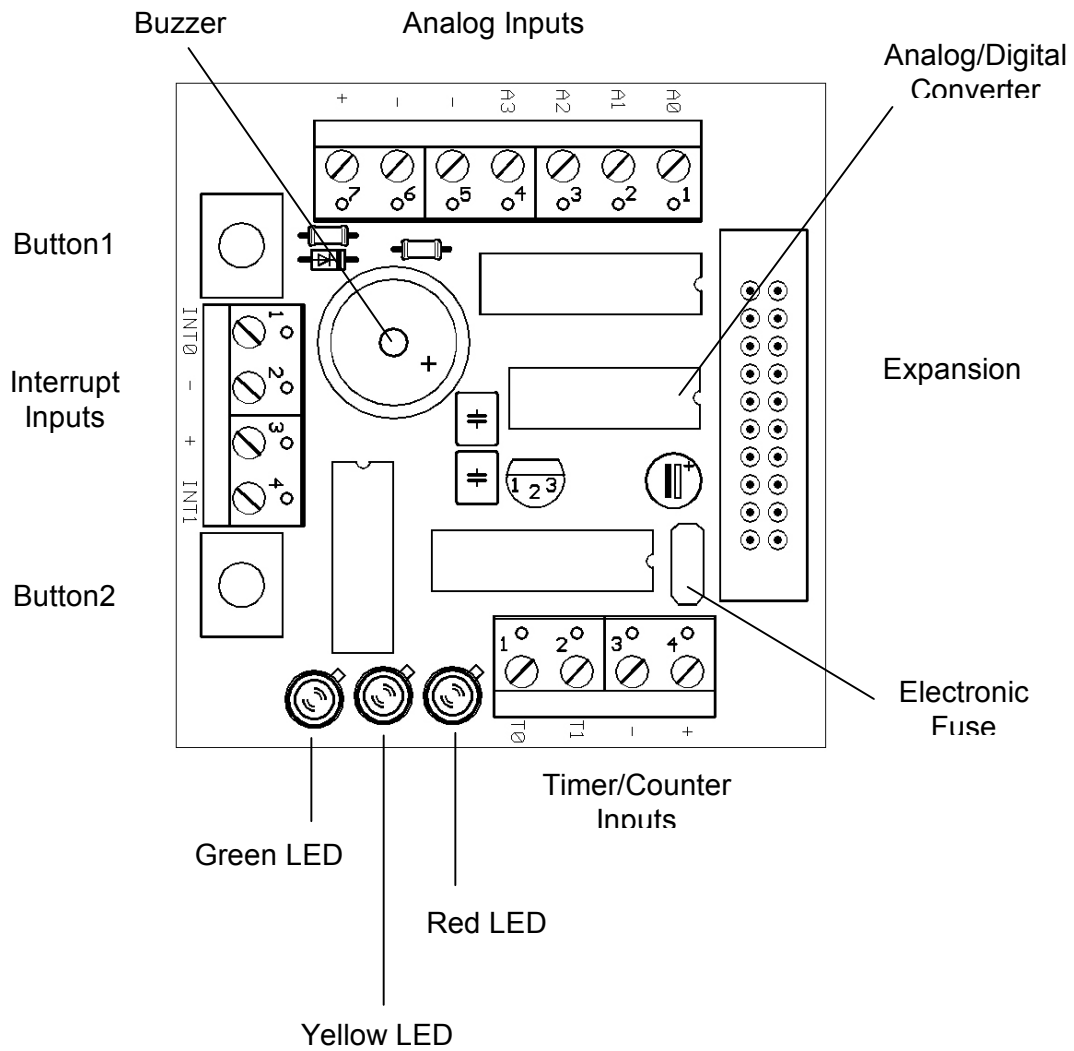
TB-1 is already connected to the MINI-MAX/P18 board as part of the MicroTRAK.

Specifications

Dimensions are 2.35 X 2.40 inches (5.97 X 6.10 centimeters).
Mounting holes of 0.125 inches (3 millimeters) on four corners.
0° - 70° C operating, -40° - +85° C storage temperature range

Board Layout

Layout of TB-1 board is shown below:



Functional Blocks

Expansion

TB-1 is connected to MINI-MAX/P18 and other boards through the Expansion Connector (J1). Table 4 shows the pin assignments for the Expansion Connector.

Expansion (J1)

Signal	Pin	Pin	Signal
P3.0	20	19	P3.1
P3.2	18	17	P3.3
P3.4	16	15	P3.5
P3.6	14	13	P3.7
P1.0	12	11	P1.1
P1.2	10	9	P1.3
P1.4	8	7	P1.5
P1.6	6	5	P1.7
VCC	4	3	GND
VCC	2	1	GND

Table 4

LED's

TB-1 has 3 Light Emitting Diodes (LED's) that are connected in a traffic light pattern. Red and green LED's are on each side and the yellow LED is in the middle.

LED's are driven by a 7407 buffer (IC2). Each LED has two pins; cathode (negative terminal) and anode (positive terminal). The current through the LED's are limited through current limiting resistors that tie the anode pins to Vcc. To turn an LED on, the cathode is pulled to ground through the corresponding gate of the 7407 buffer. To turn an LED off, the corresponding gate of the 7407 buffer is deactivated by setting the input of the gate to a logic high level.

Buzzer

Because the buzzer requires higher current than the LED's, buzzer is driven by three 7407 buffer gates that are connected in parallel. Due of the inductive nature of the buzzer, a freewheeling diode (D4) is used to clamp reverse voltages that may be induced on the buzzer when the buzzer is being turned on or off.

Buttons

There are 2 push buttons on the TB-1. Each button is connected through a protection resistor to an interrupt input (P3.2 and P3.3) on the micro-controller. Pressing a button forces a logic low level on the corresponding micro-controller input.

Interrupt Inputs

Port pins P3.2 and P3.3 can be used either as general-purpose inputs/output or as interrupt inputs. A high to low logic transition or a low logic level on those inputs can cause a hardware interrupt to be generated.

Timer/Counter Inputs

Port pins P3.4 and P3.5 can be used either as general-purpose inputs/output or as timer/counter inputs. Logic level changes on these inputs can be counted by the timer hardware on the micro-controller eliminating the need for software polling loops.

Analog/Digital Converter (ADC)

TB-1 has a type ADC0834, 4-channel, 8-bit Analog/Digital converter. Analog inputs are available on X1 terminal block. Analog/Digital Converter is controlled by the micro-controller through 4 port lines. Chip Select (CS) is an input to the ADC. Chip Select enables data conversion when it is logic low and disables data conversion when it is logic high. Clock is an input to the ADC. Mode of operation (single-ended versus differential) and channel number is entered through the DI pin one bit at a time (on every transition of the Clock input). The 8-bit data that corresponds to the voltage on the selected channel is output on DO one bit at a time (on every transition of the Clock input).

Advanced Project Ideas

- Using the MicroTRAK as a frequency counter: Student develops a PIC® program to measure the frequency and/or period of an incoming signal using PIC18F458's interrupt inputs. The results are then displayed on the terminal window. Input signal is provided from a lab signal generator.
- Using the MicroTRAK as a temperature controller: Student develops a PIC® program to connect LM35 or similar temperature sensor to the analog inputs. Depending on the temperature reading one of red, yellow or green LED's are illuminated. If the temperature goes above a preset threshold, the buzzer sounds.
- Using the MicroTRAK EEPROM and the Analog-To-Digital Converter as a multi-channel data logger.